# **SASSPR**

#### **Semi-Automated Sensing for Surface Plasmon Resonance**

#### **Group 2**

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#### **Motivation**

- Viruses such as COVID-19 show the importance of rapid and accurate drug development.
- Observing molecular binding between an analyte and ligand is a crucial step in many biological research projects, including drug development.
- SPR sensors monitor the binding kinetics of the interaction between biomolecules without the need for labels, while also providing information on the on and off rates.
- However, commercial SPR sensors are very expensive, average cost \$40,000.
- Affordable SPR sensors would provide biochemistry labs across the world with more accurate data on biomolecular interactions.

## **Goals and Objectives**

- Design a more affordable SPR sensor compared to commercial SPR sensors on the market.
- SPR sensor will be fully automated to detect the surface plasmon resonance angle and display the information to the consumer in a graphical representation.
- Sensor location will be easy to reuse, lowers the cost of consumables.
- Provides accurate data on the angle where excitation of surface plasmon polaritons (SPP) occurs.
- Experiments will be easily repeatable.

## **Biological Samples to Test**



### **How Do SPR Sensors Work?**

- SPR chip contains immobilized Protein A to the gold surface.
- **Before solution** containing IgG is added, the software detects a drop in intensity from the reflected beam.
- The reflected angle where the drop in intensity occurs is our initial SP angle, θ spo.



### **How Do SPR Sensors Work?**

- When the IgG solution is added, the antibodies begin to bind to the Protein A.
- The binding between the ligand and analyte causes the refractive index of the gold surface to change.
- The change in refractive index leads to a change in the SP angle, labeled  $\theta$ <sub>SP1</sub>, which the software detects as an increase in intensity.



# **Design Description**

#### **Step 1: Determine Initial SPR Angle**

- SPR chip is placed onto base of prism by user, affixed to surface using index matching gel.
- System turned on using software application. Laser, motorized rotation stage, camera, and MCU fully controlled using software app.
- Motorized rotation stage rotates automatically from range 42-50**°** in 0.1**°** increments.
- Camera captures 1 image every 0.5 s at every 0.1**°** increment of the rotation stage. Camera stops image capture after 50**°**.
- Application measures the intensity profile of the captured images taken during the measurements. From data, the angle where max drop in intensity occurred can be determined.
- Rotation stage is rotated to angle were max drop in intensity was observed.



# **Design Description**

#### **Step 2: Observe Molecular Binding**

- Analyte solution to be tested is added by user to sensing chamber. The rotation stage remains fixed at angle of lowest intensity.
- Camera begins capture of 1 image every 0.5 s until an increase in measured intensity is observed from intensity profile of processed images.

#### **Final Results**

- Software displays two graphs to user:
	- Intensity vs. incident angle of beam.
	- Intensity vs. time.
- Data from previous experiments will be saved by the software for future reference.



# **Engineering Specifications**



# **Hardware Design**



# **Hardware Block Diagram**



#### **Laser Diode Module**





## **Polarizing Beam Splitter**





(Coating and Cement Layer Not to Scale)

# **Motorized Precision Rotation Stage**



**Continous 360° Motorized Rotation** 25 arcsec Minimum Incremental Motion Rotational Velocity: 25 Degree/Second Compatible with Our SM1 Lens Tubes and 30 mm Cage Systems PRM1Z8





**PRM1Z8** with a WPMH05M-633 Wave Plate

## **Surface Plasmon Sensor Material**



## **Adhesive for SPR Chip**

- Gap size between prism and gold metal surface determines if incident energy from light source transfers to surface plasmon polariton (SPP) mode.
- Small air gap: leaky plasmon, incident angle not critical.
- Large air gap: narrow resonance, weak coupling of SPP.
- Intermediate air gap: almost 100% of incident energy transferred to SPP mode.
- **● Index matching gel (n=1.5) will be injected between prism and gold metal SPR chip. Ensures gold and prism remain in close contact for incident light to travel from prism to gold and transfer energy to SPP mode.**





#### **Parabolic Mirror and Plano-Convex Lens**



#### **Microcontroller Unit**



- Modified from original ESP32 to support Pseudostatic RAM and a parallel camera interface, enhancing IoT functionality
- Low-Energy Bluetooth
- Dual Wi-Fi
- Small, cheap and abundant for testing

The processing power of the ESP32 was potentially too slow for our engineering specifications but with the aforementioned qualities, we decided to work with what the device offered.

## **CMOS Sensor** . Omnivsion image sensor that



- supports up to 1600 x 1200 resolution, 15 captures per second
- Popular amongst tech giants, widely available documentation
- Onboard JPEG compression for low latency upload, removing load from MCU
- Compatible with low-end ARM microprocessors

The OV2640 was a no-brainer for its similarities with smartphone cameras which is something used often for portable SPR systems.



### **ESP32-CAM Capture vs Clock Frequency**



#### **Original Power Design (Before Rotation Platform)**

![](_page_20_Figure_1.jpeg)

#### **Perfboard for AC Adaptor and Battery Power Regulation**

![](_page_21_Picture_1.jpeg)

- Uses AC from a wall adaptor and DC from a LiPo battery, prioritizing AC when both are attached.
- Delivers power to microcontroller, laser diode, and rotation platform
- Uses 2 switching regulators
- Voltmeter to read battery charge level
- Houses transistor for binary control of power delivery to laser diode.

![](_page_21_Picture_7.jpeg)

### **3D Printed Prototype Housing**

![](_page_22_Figure_1.jpeg)

![](_page_22_Picture_2.jpeg)

![](_page_22_Figure_3.jpeg)

# **Software Design**

![](_page_23_Picture_1.jpeg)

![](_page_24_Figure_0.jpeg)

# **Kivy Python Framework**

- Written entirely in Python
- Fast response time to fulfill capture rate requirement
- Compatible with MacOS, iOS, Android, and Windows.
- Free and Open Source meaning wide availability of addons, libraries and documentation
- Enables rapid prototyping by building the application for all compatible systems

![](_page_25_Picture_6.jpeg)

# **Prototype Software Solution for FASSPR**

**C**FASSPR  $\times$ Execution Interval: 0.325 Average Runtime: 0 Capture Count: 0  $FPS: 0$ 09/12/2021 - 02:52 PM **Start Capture Stop Capture Toggle Laser Rotation Platform Check Battery Restart MCU** 

- Variable execution interval to maintain desired capture rate.
- Control over power delivery to laser diode.
- Control over motorized rotation platform
- Verify power source from wall or battery and check battery level
- Measure and record brightness of captured images and graph them over time
- Store and retrieve past experiments
- Compatible with Windows, Android, Mac OS and iOS

# **Administrative Content**

#### **Work Distribution**

![](_page_28_Picture_53.jpeg)

## **Project Budget and Financing**

![](_page_29_Picture_4.jpeg)

## **Project Challenges**

![](_page_30_Picture_85.jpeg)

## **Potential Redesign 1: Moveable Laser Stage**

- Mount the laser onto a mechanism that changes the incident angle of laser.
- Used to detect changes in angle of SPP as analyte solution added to sensing location.
- Added cost:  $\ge$  \$1,000

Laser stage

![](_page_31_Figure_5.jpeg)

## **Potential Redesign 2: Galilean Beam Expander**

- Place an achromatic AR-coated Galilean beam expander after the polarizing beam splitter.
- Expands the diameter of the beam, allows us to monitor the change in surface plasmon resonance angle as analyte solution introduced.
- Added cost: \$400-\$500

![](_page_32_Figure_4.jpeg)

![](_page_32_Figure_5.jpeg)

## **Current Progress and Future Plans**

#### **Current Progress**

- Camera and microcontroller is working, camera can capture 1 image every 0.5 seconds.
- Power supply has been designed, however redesign is required to incorporate the motorized rotation stage.
- Software application in development, prototype designed and tested. Collects and processes the data in less than 500 ms.
- 3D printed prototype of casing for laser diode module created, a second prototype will be designed to properly attach to new laser diode dimensions.
- Optical equipment has been ordered and delivered as of September 16, building of optical setup for testing can begin.

#### **Future Plans**

- Research Galilean beam expander, determine if appropriate for current system.
- Redesign power supply to include motorized rotation stage.
- Redesign software application for communication with motorized rotation stage.
- Create surface plasmon excitation with current optical setup.
- Build prototypes of housing unit and casing for each optical and electrical component.
- Purchase biological samples and begin testing for molecular binding.

![](_page_34_Picture_0.jpeg)

![](_page_34_Figure_1.jpeg)

![](_page_35_Picture_0.jpeg)