OUC All-in-One Photovoltaic Sensor

Group 5

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Motivation



In order to be a convincing replacement for traditional fossil-fuel power sources, solar technology needs to be powerful and efficient.

As such, lots of research is done in the manufacturing of new solar panel technology. However, solar farm operators often have limited access to panel level data.

Our goal is to create a device which will give solar farm operators a simple and expandable way of collecting panel level data. It should work on a variety of solar arrays, whether they be small research arrays with a variety of different panels, or a production scale power generation array.

Project Goals and Objectives



Our **primary goal** is to create several prototypes of a photovoltaic sensor applicable in small-to medium-scale solar arrays that determine panel health by monitoring its voltage and amperage.

Our **secondary goal** is to incorporate two supplementary measuring instruments to our original design: a thermocouple capable of tracking panel temperature and a pyranometer that can detect incident light irradiance.

When installed in a solar array, the sensor will collect panel health data which the operator can then use to optimize the longevity and consistency of the array's power generation.

Specifications and Requirements

Engineering Requirements

32V Rating 10A Rating 320W Rating (On Terminals) ≥ 1 Year Lifespan Under \$20 each

Marketing Specifications

Use MC4 connectors Transfer data to database NEMA 4X or 4R Enclosure Comply with FCC standards Filter out noise Portable Connect between solar panels Reproducible Connections for thermocouple and pyranometer

High High High Moderate Low Priority High High High High Moderate Moderate Moderate Moderate Iow

Priority

Demonstrable Specifications

Voltage Measurement Accuracy Current Measurement Accuracy Data Transmission

These specifications are directly from OUC, as the voltage and current are most important in getting accurate panel health readings.

±5%

±5%

≤ 10s



Project Standards

Project Standards: Enclosures



NEMA 250

NEMA 250 provides the standards of ingress protection tests for all of the enclosure types, from Type 1 to Type 13.

For our project, the OUC required a NEMA Type 4X enclosure, which establishes:

- Access to hazardous parts
- Ingress of solid foreign objects (falling dirt)
- Ingress of water (dripping and light splashing)
- Ingress of water (rain, snow and sleet)
- Ingress of solid foreign objects (windblown dust, lint, fibers and flyings)
- Ingress of water (hose-down and splashing water)
- Corrosive agents



Project Standards: Enclosures (ctd.)

IEC 60529

A standard from the International Electrotechnical Commission that establishes a system for classifying levels of protection provided by enclosures. There are different degrees of protection laid out in the standard. The one with which we are concerned is IP66.

This rating offers complete protection of the internal components from anything equal to or larger in size than dust particles.

This rating also offers complete protection against power water jets. This would include any type of power water hose, which could be encountered in the outdoors area on OUC's property.



Project Standards: Pyranometers

IEC 61724-1:2017

- IEC's assessment of solar irradiance measurement
- Created classifications for pyranometers and their appropriate application
- Defined new methods of upkeep for the devices



Project Standards: Thermocouples

IEC 60584-1:2013

- IEC's internationally-recognized classification system
- Distinguishes each device's material properties

Project Standards: MC4



IEEE 802.15

IEEE 802.15 defines the protocol and compatible interconnection for data communication devices using low-data-rate, low-power, and low-complexity short-range radio frequency (RF) transmissions in a wireless personal area network (WPAN).

Project Standards: Software



Python Enhancement Protocol (PEP) 8 -- Style Guide for Python Code

PEP 8 establishes coding conventions for the Python code comprising the standard library in the main Python distribution.



Project Design Approach

Project Design Implementation



We want to create a simple sensor that provides convenient and accurate data to the Orlando Utilities Commission.

The primary purpose of the device is to collect voltage and current data, but if possible we will also seek to implement temperature and irradiance sensing.

This will enable OUC and other utility companies to better track the health of their solar installations.

The sensor will wirelessly transmit the data to the node, which will be accessible over ethernet to the commission.

Reference Design



Texas Instruments' TIDA-00640 design provides an overview on how to design a solar module-scale monitoring and communication system.

Component	TIDA-00640
PSU	LM5017
Amplifier	TLV342A
ADC	On-board the CC2538
Signal Transmission	CC2538 to RF Antenna



Prototype Visualization











Block Diagram

Software Workflow



Sensor Hardware Selection

Core Requirements:

- Read an analog input signal
- Wireless communication

Other Considerations:

- Price
- Ease of use
- Size
- Power consumption



Characteristic	Raspberry Pi Zero W	Banana Pi BPI-M2 Zero	Orange Pi i96	
Processor ARM1176JZF 1 GHz		H2+ Quad-core Cortex-A7	Single-core ARM Cortex-A5 32bit	
Processor DMIPS/MHz	1.25	1.9	1.57	
RAM	512 MB	512 MB	256 MB	
Bluetooth Capability	Bluetooth 4.1, BLE		Bluetooth 2.1	
Operating Temperature Range	0 °C to 70 °C	N/A	-10 °C to 65 °C	
Dimensions and Weight 65mm x 30mm 9g		65mm x 30mm 15g	60 mm x 30mm 30g	
Price	\$10.00	\$30.00	\$12.00	

Raspberry Pi Zero W

Why the Pi?

- Documented compatibility with MCP3008 ADC
- Bluetooth and Bluetooth Low Energy capable
- Only \$10.00
- Lots of community support
- Very small (66.0mm x 30.5mm x 5.0mm)
- Less than 1.0W power consumption with Bluetooth on





Node Hardware Selection

Core Requirements:

- Bluetooth communication
- Expandable storage

Other Considerations:

- Price
- Ease of use
- Size
- Power consumption



Characteristic	Raspberry Pi 4 Model B	Banana Pi BPI-M5	NanoPi M4B	
Processor	Broadcom BCM2711, Quad core Cortex-A72 (ARM v8) 64-bit SoC @ 1.5GHz	Amlogic S905X3 Quad-Core Cortex-A55 @ 2.0 GHz	Dual-Core Cortex-A72 @ up to 2.0GHz + Quad-Core Cortex-A53 @ up to 1.5GHz	
RAM	1 GB - 8 GB	4 GB	2 GB	
PoE Support	Yes - w/ PoE HAT (\$20.00)	Νο	Νο	
Bluetooth Capability	Bluetooth 5.0, BLE	None	Bluetooth 5.0	
Operating Temp. Range	0°C to 70°C	N/A	-20°C to 70°C	
Price	\$30.00	\$60.00	\$70.00	

Raspberry Pi 4 Model B

Why the Pi?

- Bluetooth and Bluetooth Low Energy capable
- Only \$30.00 for 1GB RAM model
- Lots of community support
- Fits easily within our enclosure
- Less than 6.5W power consumption under full load
- Approximately 3W idle power consumption





Circuitry Hardware Selection



- 1. Read voltage across and current through the panel
- 2. Have an onboard power supply convert panel voltage to board voltage
- 3. Amplify the voltage and current values for ease of conversion
- 4. Convert the analog values to digital and transmit

Other Considerations:

- 1. Power consumption we need to avoid having full power (300 W) on the PCB We chose low-power components and high-value resistors to ensure this
- 2. Price total cost of parts + board should be under \$20 We chose common, general purpose parts to keep the cost low
- 3. Size should be similar in size to a Raspberry Pi handheld Since we have small parts, we accomplished this
- 4. Ease of use should be able to plug-in and start measuring data The hardware will always start up right away, and the software automatically starts up after the RPi Zero W boots up.

The Amplifier

This part of our design takes the analog measurements from the solar panel and prepares them for conversion through amplifying them.

The voltage reading, being divided by 8 through the voltage divider, is amplified by a gain of 1. This gets rid of the Loading Effect as well.

The amperage reading, being represented by a voltage from the shunt resistor, is multiplied by 85, as it starts as a small voltage and needs to be larger for the ADC to pick it up.

Voltage	Voltage Divider Reading	ADC Value
8V	1V	205
12V	1.5V	307
16V	2V	410
20V	2.5V	512
24V	3V	615
28V	3.5V	717
32V	4V	819

Voltage Divider







The Amplifier



Our first choice was the TL072, as it seemed the best for our maximum voltage.

Ор Атр	Channels	GBW (MHz)	Max Supply	Output Current	Temperature Range (°C)	Cost (each)
TL072	2	3	30 V	10 mA	0-70	\$ 0.075
NE5532	2	10	30 V	38 mA	0-70	\$ 0.296
RC4558	2	3	30 V	10 mA	0-70	\$ 0.055
LM358B	2	1.2	36 V	30 mA	-40-85	\$ 0.051
LM741	1	1	44 V	25 mA	0-70	\$ 0.236
		Table 9: O	perational A	mplifier Com	parison	1

The DC-DC Converter

Our priorities for the DC-DC converter:

- 1. High efficiency
- 2. Low BOM cost and count
- 3. Low ecological impact

Option	Part #	Efficiency (%)	BOM Cost (\$)	Footprint (mm ²)
1	LMR36506RF3	64	1.29	112
2	LMR50410X	81.6	0.70	142
3	LMZM23600V3	79.5	2.32	41
4	TPSM265R1V3	71.7	1.98	40
5	LM317	9.8	0.4	357
k i		able 8: Potential I	Power Supply Desig	TNS

The Analog-to-Digital Converter

Our priorities for the analog-to-digital converter:

- 1. Run efficiently from 5 V supply voltage
- 2. Ease of interfacing with the Raspberry Pi Zero
- 3. Have reasonably high resolution; enough for 2-decimal place accuracy.

Why the MCP3008?

- No need for higher resolution and the corresponding price
- Use of SPI rather than I2C protocol
- Ease of use

Over the length of our project, the ADC was one of the most stable and robust parts of the overall design, so we did not need to change it out for a better package.

ADC Device	MCP3008	ADS1015	ADS1115
Channel Count	8	4	4
Resolution	10-bit	12-bit	16-bit
Sample Rate	200,000	3,300	860
Cost	\$3.75	\$9.95	\$14.95
Interface	SPI	I2C	I2C
Table 13	. The summarized chara	cteristics of the prospection	e ADCs

The Pyranometer





Our priorities for the pyranometer:

- 1. Read the irradiance surrounding the panel
- 2. Transmit the value to the ADC
- 3. Do it all at a low cost

Option	Design	Self-powered?	Output	Price
1	Thermopile	Y	Calibrated output of up to 100 mV	\$333
2	Silicon Cell	Y	Calibrated output of up to 400 mV	\$233
3	Thermopile	Ν	Internally converts output to digital	\$433
4	Silicon Cell	Ν	Internally converts output to digital	\$323

The Pyranometer

Why the SP-110-SS: Self-Powered Pyranometer?

- Lightning fast response time
- Self-powered
- Inexpensive
- Fits our design without superfluous features
- Best mV output range for the ADC





The Thermocouple



Our priorities for the thermocouple:

- 1. Read the temperature of the immediate panel area
- 2. Transmit the value to the ADC
- 3. Do it all at a low cost

Why the T-type thermocouple?

- -330 600 °F range
- Margin of error of 0.4-0.75%

Туре	Metallic Composition	Temp. Range (°F)	Margin of Error (%)
K	Nickel, Chromium, Aluminum, Manganese, Silicon	200 - 2300	0.4 - 0.75
J	Iron, Constantan	200 - 1400	0.4 - 0.75
Т	Copper, Constantan	-330 - 600	0.4 - 0.75
E	Nickel, Chromium, Constantan	200 - 1650	0.4 - 0.5
N	Chromium, Silicon, Magnesium, Nickel	1200 - 2300	0.4 - 0.75
S	Platinum, Rhodium	1800 - 2640	0.1 -0.25
R	Platinum, Rhodium	1600 - 2640	0.1 - 0.25
В	Platinum, Rhodium	2500 - 3100	0.25 - 0.5

Initial Design: Version 1.0







How Our Design Works





Testing 1.0

Power Supply

Testing Round 1: Power Supply gave a constant output, but wrong value.

Testing Round 2: Circuit restructuring gave us the output we need, consistently.



Test 1 PSU





Amplification

Data so far:

Input 1 (Range): 1-3 V Input 2: 0.01 V

Need input range of 0-4 V

TL072 range - 4-5 V inputs TLV342A range - 0-4.4 V

This is assuming a 5 V value for VCC.



3

2

0

ADC

Testing

The testing setup was simple:

- Connect to the Raspberry Pi
- Use Power Supply as analog
- Convert to digital
- Transmit and read data

The columns represent the different inputs of the ADC.

VCC = 5V w/ 1024 steps → 0.00488V/step

Column 1 = 2VVoltage ReadingColumn 2 = 0.06VPyranometerColumn 3 = 1.5VCurrent Reading

le Edit	Tabs	Help						
409	0 1	305 1	31	0	0.1	0.1		
409	0	306	7	0	0	0	0	
410	0	206	-		0	0	0	
410	0	300	2	U	0	0	0	
410	U	300	4	0	0	O	0	
409	0	306	4	0	0	0		
410	1	306	4	0	0			
409	13	309	6	0	0			
409	13	305	3	0	OI	0 1		
410	13	306	5	0	0	0 i	Θİ	
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409	14	306	5 1	0	Θİ	0 1	Θİ	
410	14	306	1	0	0	0 1	οi	
410	13	306	11	0	0	0	οi	
410	13	306	2	0	0 1	Θİ	οi	
400	13	306	1	0 1	0	O	Øİ	
410	12	306	0	0	0	0	0	
409	12	306	2	0	.0	0	0	
409	12	306	Ø	Θ	0	O	0	
409	12	306	0	0	0	0	0	
409	11	306	2	0	0	0	0	
1 410	11	306	3	Θ	0	0	0	
410	10	306	2	Θ	0	0	0	

Initial PCB



• Once we verified that the design functioned properly, we ordered the first version the PCB:







Testing 2.0

Testing 2 (w/ the initial PCB)

Testing the amplifier circuit and the PSU.



Testing 2 (w/ the initial PCB) (ctd.)

Testing the data communication.



PCB Design 2.0



After realizing we would not have enough power supplies, we realized we needed to purchase more. However, the LMR50410X was on backorder.

Fortunately, we were able to secure its sister components: LMR14010ADDCT and LV2862XLVDDCR. They both had the same layout, only differing in the values of the various components in the layout.

Converter	Efficiency	BOM Cost	Footprint
LMR50410	81.6%	\$0.70	142 mm^2
LV2862	87.7%	\$1.35	246 mm^2
LMR14010	86.4%	\$1.41	218 mm^2



The two power supplies did require slight changes on the PCB design, however. These changes included:

- A schottky diode
- More capacitors

We also changed the board layout by moving the capacitors closer to the PSU IC in order to reduce the effects of ripple voltage.

PCB Design 2.0 (ctd.): LMR50410X Schematic



PCB Design 2.0 (ctd.): LV2826 schematic





PCB Design 2.0 (ctd.): LMR14010 schematic







- We saw in testing that the minimum voltage of the amplifier was not low enough.
- We decided on getting the TLV342A, which had a minimum voltage input of 0 V.
 - However, the input offset voltage was high enough that it interfered with the amperage reading.
- Then we got the TSZ122IDT Because of its input offset of only 8 uV.

Amplifier	Manufacturer	Offset Voltage	Cost
TL072	Texas Instruments	6mV	\$0.08
TLV342A	Texas Instruments	0.3mV	\$0.33
TSZ122IDT	STMicroelectronics	8uV	\$2.50



 Note the Raspberry Pi mounted onto the board.





There are a few things to note in differentiating between the two versions of the PCB.

- The PSU layout becomes more robust.
- The shunt resistor package greatly increases.
- The GPIO header is flipped to accommodate the Pi Zero.
- Capacitors are placed closer to components.
- The signal planes get more streamlined.



Testing 3 (w/ the PCB 2.0)

Testing the PSU.



Testing 3 (w/ the PCB 2.0) (ctd.)

Testing the amplifier circuit and the ADC circuit.



Results (Voltage Accuracy)



The final prototype contains a fully functional power supply unit (PSU).

Input Voltage (V)	8.000	16.000	24.000	32.000
PSU Output (V)	5.000	5.000	5.000	5.000
Percent Error	0%	0%	0%	0%

With a steady 5V power supply from the PSU, the (voltage) amplifier functions properly and accurately as well.

Specification:

Voltage measured within 5% of real value.

Result:

Average percent difference between expected and actual of 0.76%, with a maximum of 1.38%.

Expected vs. Actual Voltage Measurement



Results (Amplifier)



The amplifier also is responsible for measuring the current flowing through the panel. However, our amplifier could not get an accurate reading of the input current.

- The low current consumption by the sensor could be so small that the amplifier circuit could not register the value properly.
- Another possibility could be the input offset voltage of the amplifier. The amplifier we are using (TL072) may have an input offset voltage that is too high, causing the amplifier to malfunction.

Results (ctd.)

The ADC is also able to translate the pyranometer values as well.



Results (ADC Circuit)



Although we were able to obtain a functioning ADC circuit, we were not able to transmit the temperature values. Even while using the thermocouple provided by OUC, the readings from the thermocouple were always inaccurate.

The voltage measured between the two leads was consistently inaccurate.

This issue could be rectified in potential future designs by supplying a voltage to the thermocouple from the 5 volt DC power converter, which would allow the ADC to detect changes in voltage input due to changes in the thermocouple resistance due to temperature. Regardless, this was a low priority for our sensor.

Results (Data Transmission)



The data transmission time is measured from when the node requests data from a sensor, to when that data is inserted into the local database on the node.

Tracking this transmission time across 10,000 data transfers revealed an average of **50 milliseconds**.

The maximum transfer time was 672 milliseconds.



Administrative Content

At This Moment In Time



Our design required tweaking, but we believe it is sound. Field testing has been completed.

Milestone Part Selection Protoboard Design	Status 100% 100%	- Initial Design/Schematic
Protoboard Testing	100%	- Breadboard Testing
Analog to Digital Signal Conversion	100%	
Bluetooth Transmission	100%	- Code Testing
Database	100%	
Construct First Prototypes	100%	- Field Testing
Field Testing	100%	
PCB Design	100%	- Ordering/Final Design
Enclosure Design	100%	

Developmental Budget

4 3

3

3

8

Component
NEMA 4X Enclosure
Pyranometer
T-Type Thermocouple
Mounting Materials
RPi Zero W
RPi 4B
Raspi PoE Hat
PCB
ICs
Various components

Quantity	Cost per
4	\$71.97
3	\$223.00
3	\$ 10.00
Varies	Varies
3	\$10.00
1	\$30.00
1	\$20.00
8	\$3.75
3 (5 copies ea.)	Varies
104	Varies

Each

Estimated Total Cost \$287.88 Provided by OUC Provided by OUC \$167.74 \$30.00 \$30.00 \$20.00 \$43.50 \$58.90 \$77.65

Grand Total \$715.67



Cost per Sensor

Component	Quantity	Cost
NEMA 4X Enclosure	1	\$71.97
Mounting Materials	Varies	<u>\$4.96</u>
RPi Zero W	1	\$10.00
PCB	1	\$3.75
MCP3008 ADC	1	\$3.75
TSZ122IDT Amp	1	\$2.50
LMR50410X PSU ^[1]	1	\$1.47
LMR14010ADDCT PSU ^{[1][2]}	1	\$1.08
LV2862XLVDDCR PSU ^{[1][2]}	1	\$1.36
Various Components	14/15	\$10.45/\$11.20

[1] Only 1 of the three PSUs are required[2] Requires diode (extra component)

Total Cost for One Sensor (w/ enclosure) \$111.84

Total Cost for One Sensor (w/o enclosure)

\$34.91



In The Future



- Learn more about the DC optimizers used in the array, and why they behaved as they did when our device was connected.
- Confirm accuracy of the current measurement when the input amperage is higher, as well as when using the newest and most precise amplifier.
- Route power to thermocouple and calibrate software to provide an accurate temperature reading.
- Standardize the distance between thermal vias on the PCB.
- Install device in enclosure to test prolonged exposure to weather.

Work Distribution



Task	Christian Avalos	Julian Gentry	Ryan Kehrmeyer	Zoran Kolega
Standards Research	*	*	*	*
Past Effort Research		*		
Software Research				*
Hardware Research	*	*	*	*
Software Implementation				*
Hardware Implementation		*	*	
PCB Design	*	*	*	
Enclosure Design	*			

