



Smart Mirror

Group K

Hector Zacarias | EE

Justin Gentry | CpE

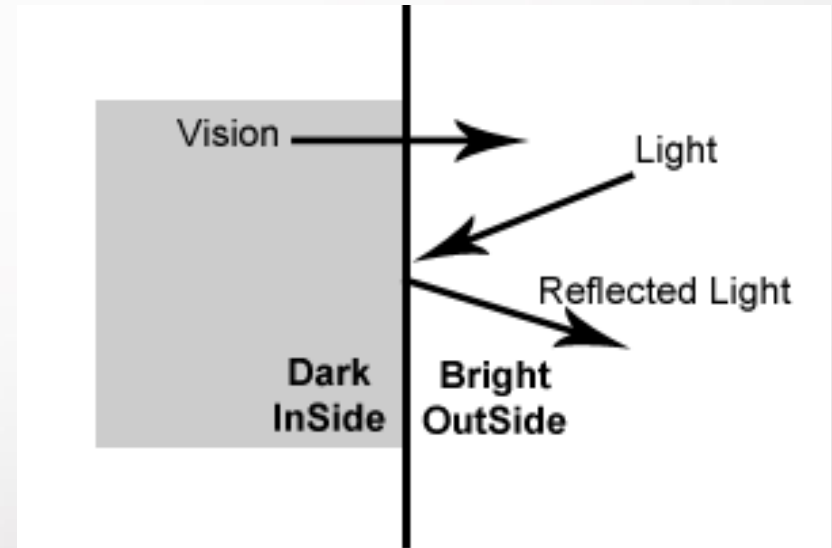
Michael Trivelli | CpE

Motivation

- Seamless integration of technology into people's daily lives
- Smart Home technology is a blooming new field
 - Google Home (Nest)
 - Amazon Echo
 - Windows 10 IoT
- Extend the idea of a 'Digital Assistant' to a room people use every morning

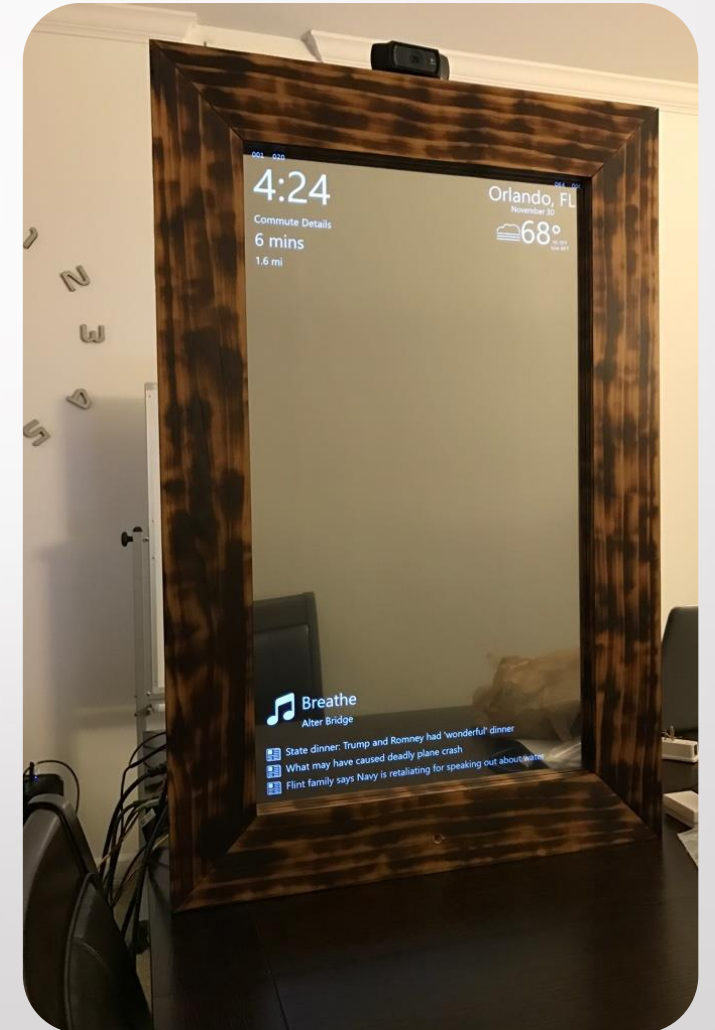
What Is It

- One-Way Mirror in front of large display
- White/Light-colored pixels bleed through mirror
- Dark pixels appear off and mirror reflects



Goals and Objectives

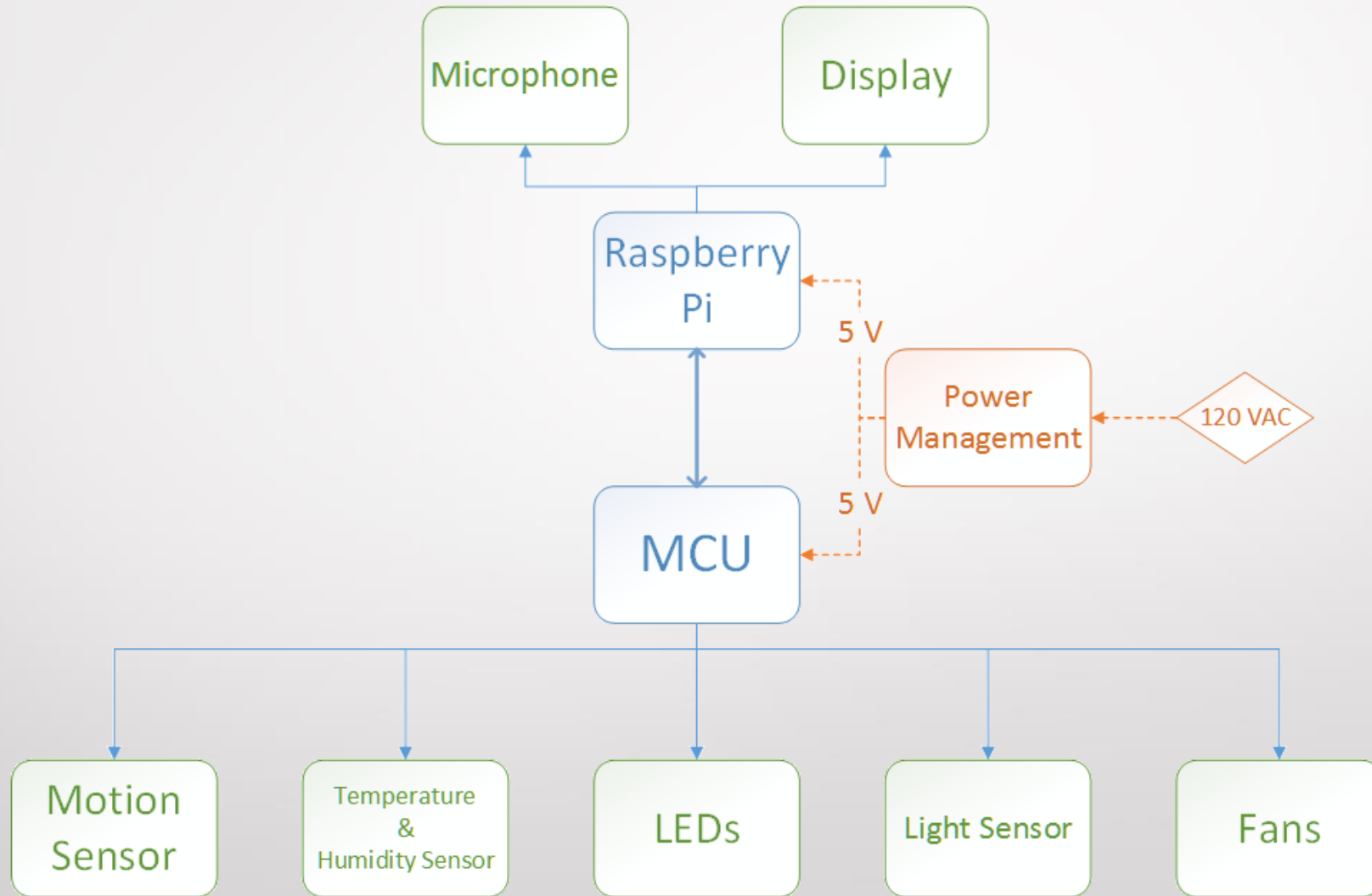
- Quality of Life improvement in the mornings
- Provide users with information they utilize regularly
- Implement a convenient user interface
 - Voice Commands
 - Limited Gesture Control



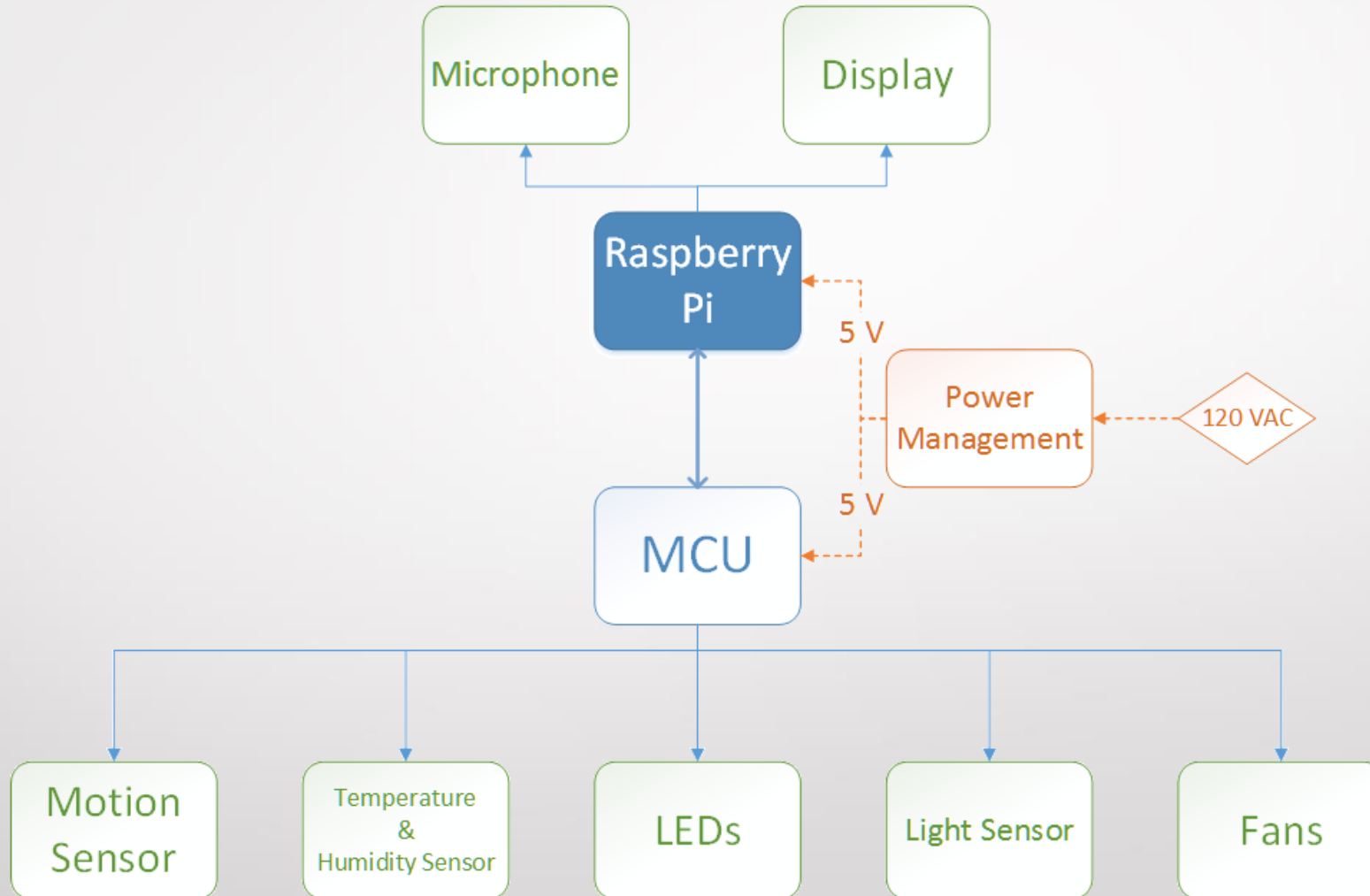
Specifications

| Voice Recognition Range | Up to 5 Feet |
|----------------------------------|--|
| Voice Recognition Success Rate | >80% |
| Display Auto-Off | After 2 Minutes of No Motion Detection |
| Temperature Sensor Accuracy | +/- 1 °C error |
| Humidity Sensor Accuracy | +/- 2.5% error |
| Motion Detection Distance | 5 Feet |
| Gesture Recognition Success Rate | >90% |

Overall Hardware Diagram



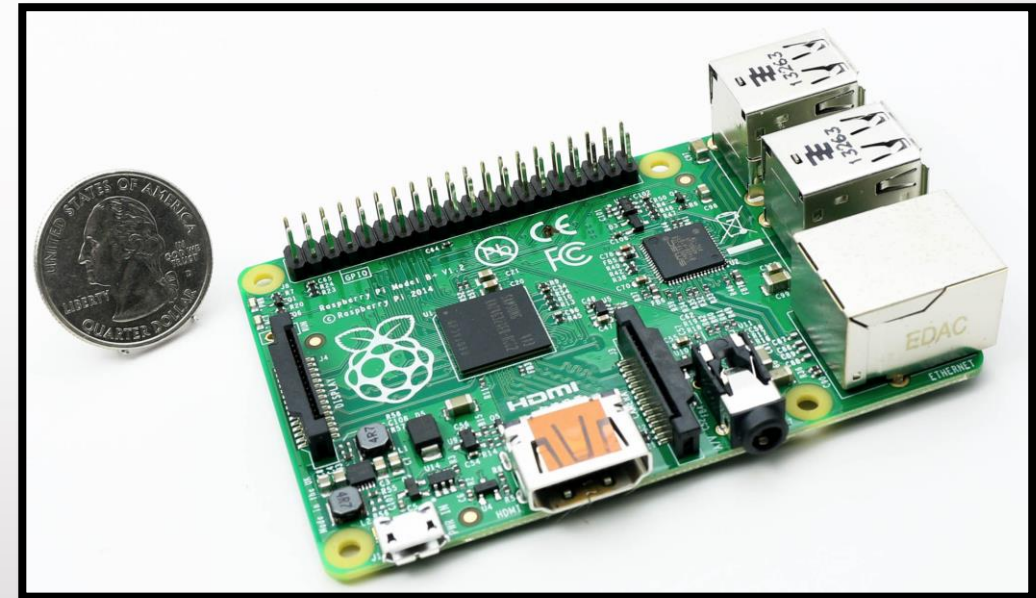
Raspberry Pi



Raspberry Pi 2

Raspberry Pi 2 Model B

| | |
|---------------------|-----------------------------------|
| CPU | Broadcom Quad-Core ARM7 900MHz |
| Memory | 1GB SDRAM |
| Storage | 8GB microSD |
| Power Supply | 5V microUSB |
| Wi-Fi Module | 802.11b/g/n |
| Video | HDMI 1.4 |
| Audio | 3.5mm Audio Port |
| USB | 4x USB 2.0 |
| GPIO | 40 pin extended GPIO |
| OS | Windows 10 – IoT Core |



Price: \$35

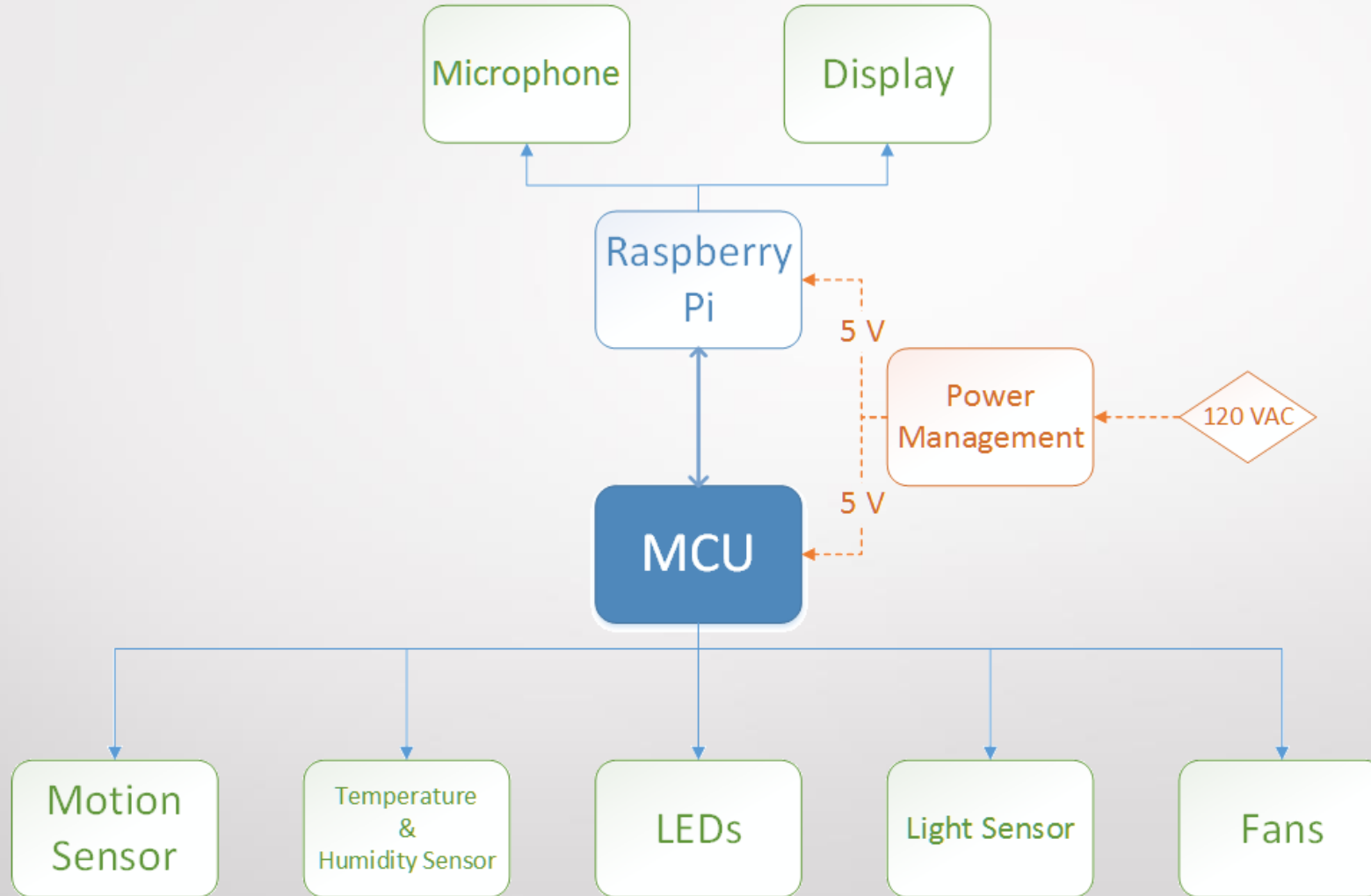
Size: 86mm x 57mm

Raspberry Pi vs Minnowboard

- Minnowboard MAX
 - Higher cost
 - \$139
 - More powerful
 - Doesn't meet requirements for Microsoft Kinect

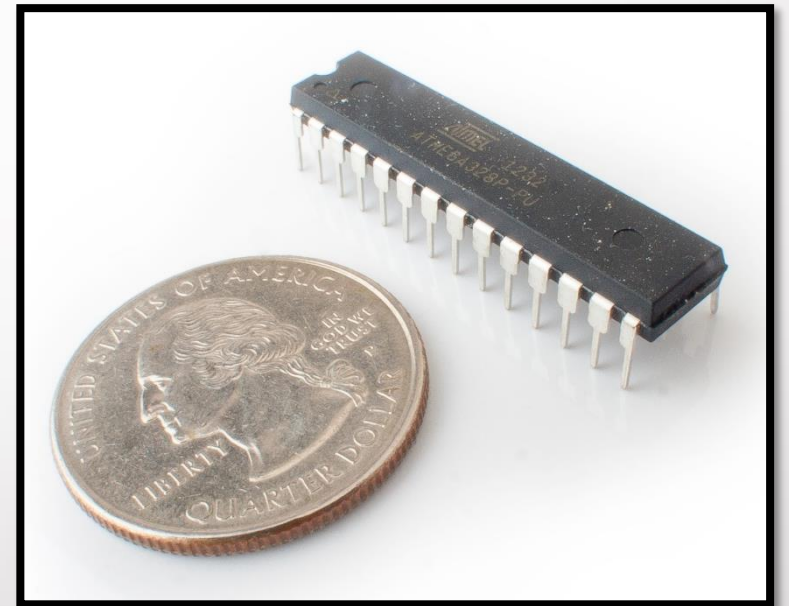


MCU

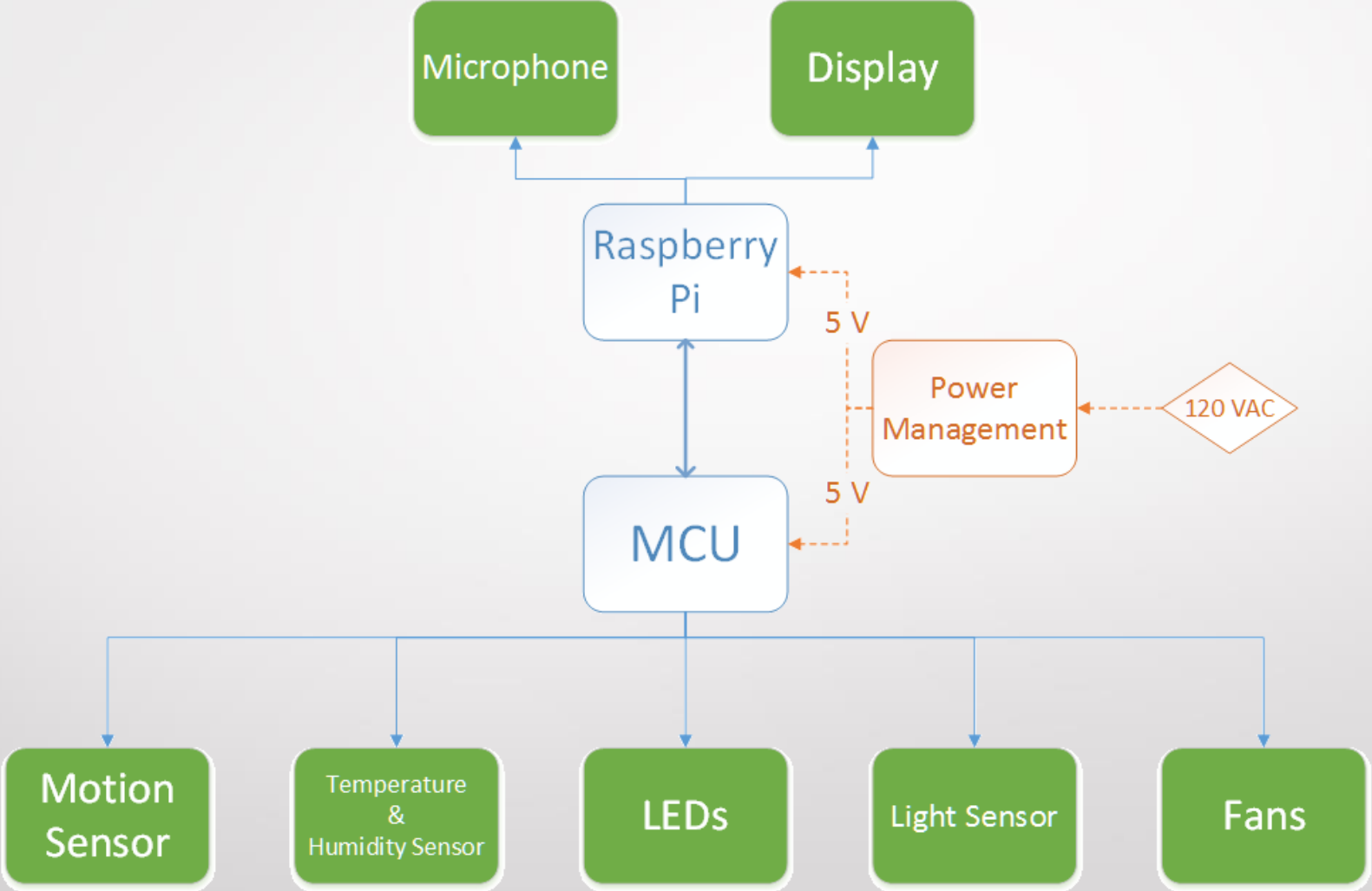


MCU Specs

| Parameter | ATmega328-PU | MSP430 |
|----------------------------|--------------|--------------|
| Operating Voltage | 1.8 to 5.5 V | 1.8 to 3.6 V |
| Operating Temperature | -40 to 80 C | -40 to 85 C |
| EEPROM | 1 KB | - |
| SRAM | 2 KB | 512 B |
| Digital Pins | 14 | 6 |
| Analog Pins | 6 | 8 |
| Clock Speed | 16 MHz | 16 MHz |
| Price of Development Board | \$9.99 | \$19.81 |

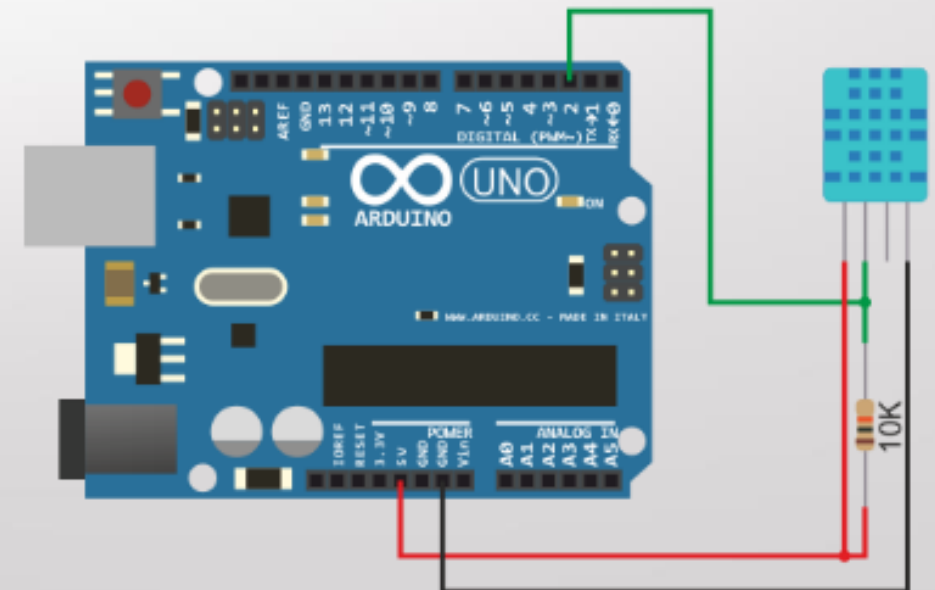
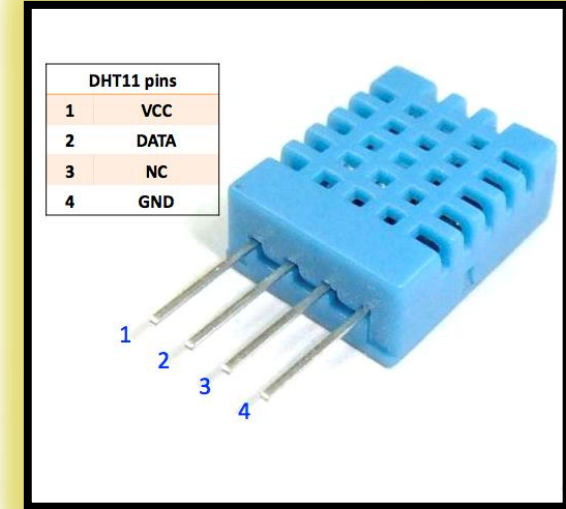
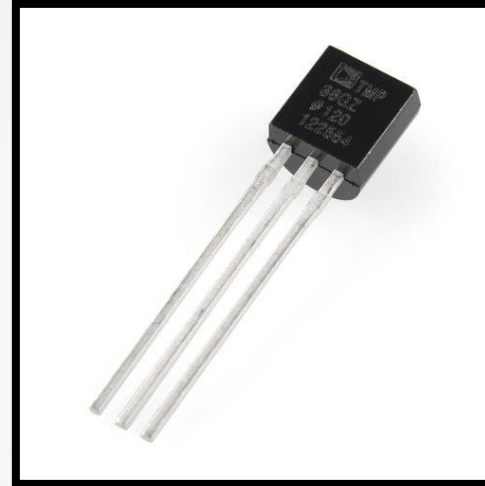


Sensors



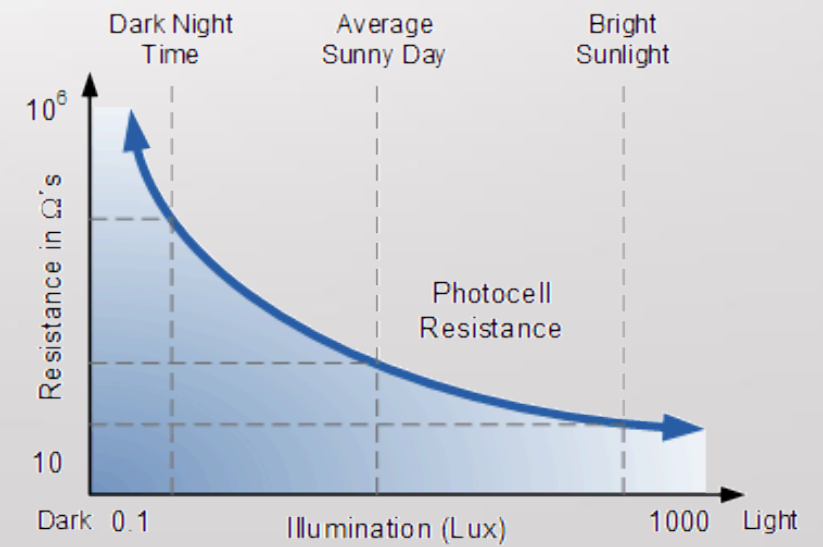
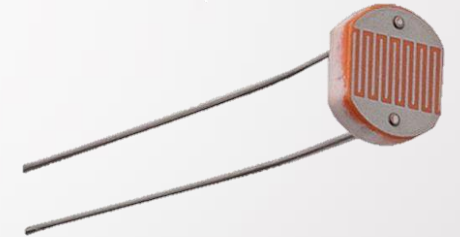
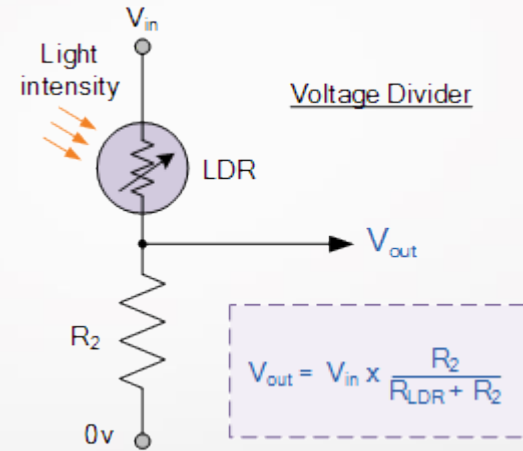
Temperature & Humidity Sensor Specs

| Parameter | TMP 36 | DHT11 |
|-----------------------------|-------------|-------------|
| Voltage Supply | 2.7 to 5.5V | 3 to 5.5V |
| Current Supply | <50 μ A | 0.5 mA |
| Humidity Temperature Range | N/A | 20 to 95% |
| Operating Temperature Range | -55 to 150C | 0 to 50C |
| Accuracy (Humidity) | N/A | +/- 5% RH |
| Accuracy (Temperature) | +/-2C | +/-2C |
| High Chemical Resistance | N/A | low |
| Hysteresis | N/A | +/-1.0 % Rh |
| Response Time | N/A | 6 s |
| Price | \$3.79 | \$1.75 |



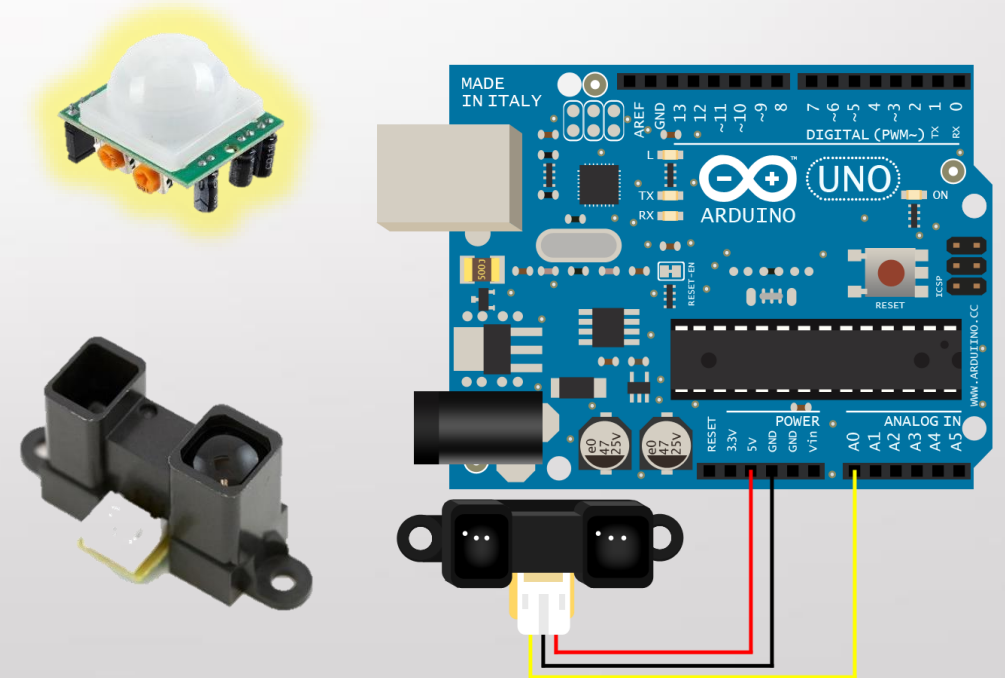
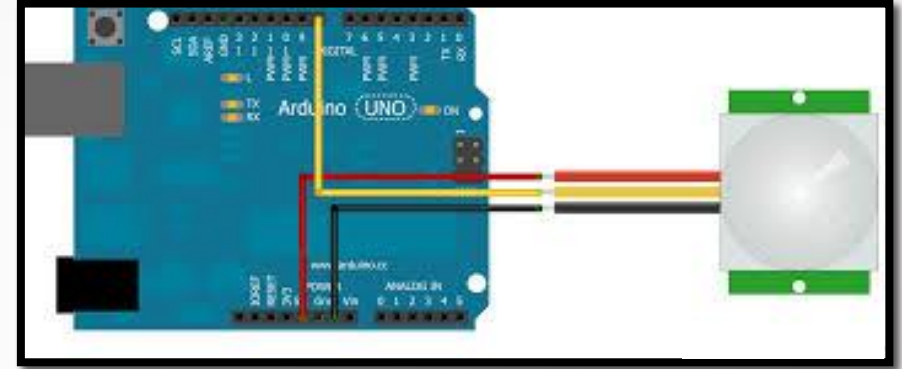
Light Sensor Specs

- Converts light energy into an electrical signal output
- A piece of exposed semiconductor changes its electrical resistance



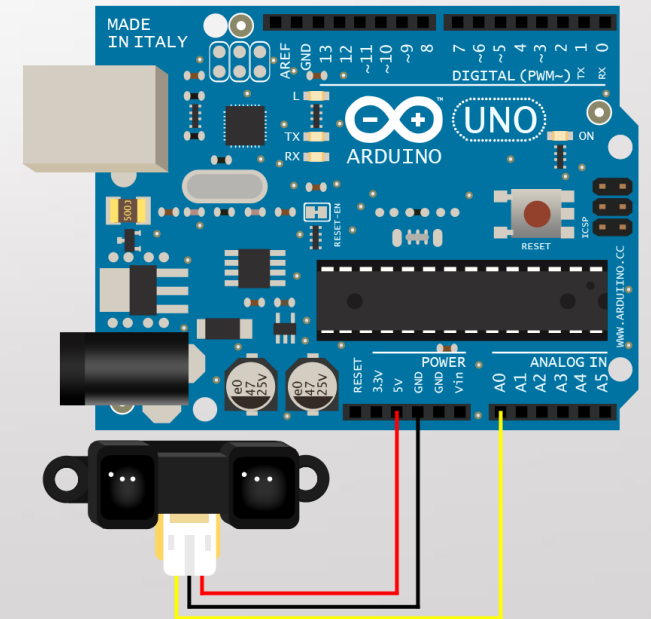
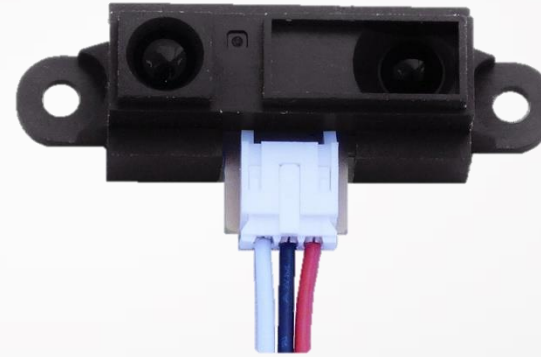
Long Range Motion Sensor Specs

| Parameter | HC- SR501 | GP2Y0A02YKoF |
|--------------------------|-------------|--------------|
| Voltage Supply | 5 to 20 V | 4.5 to 5.5V |
| Current Supply | 65 mA | 33 mA |
| Output type | Digital | Analog |
| Output Voltage | 3.3V | -0.3 to 5.7V |
| Maximum Sensing Distance | 7m | 150 cm |
| Operating Temperature | -15 to 70 C | -10 to 60 C |
| Price | \$1.80 | \$12.95 |



Short Range Motion Sensor Specs

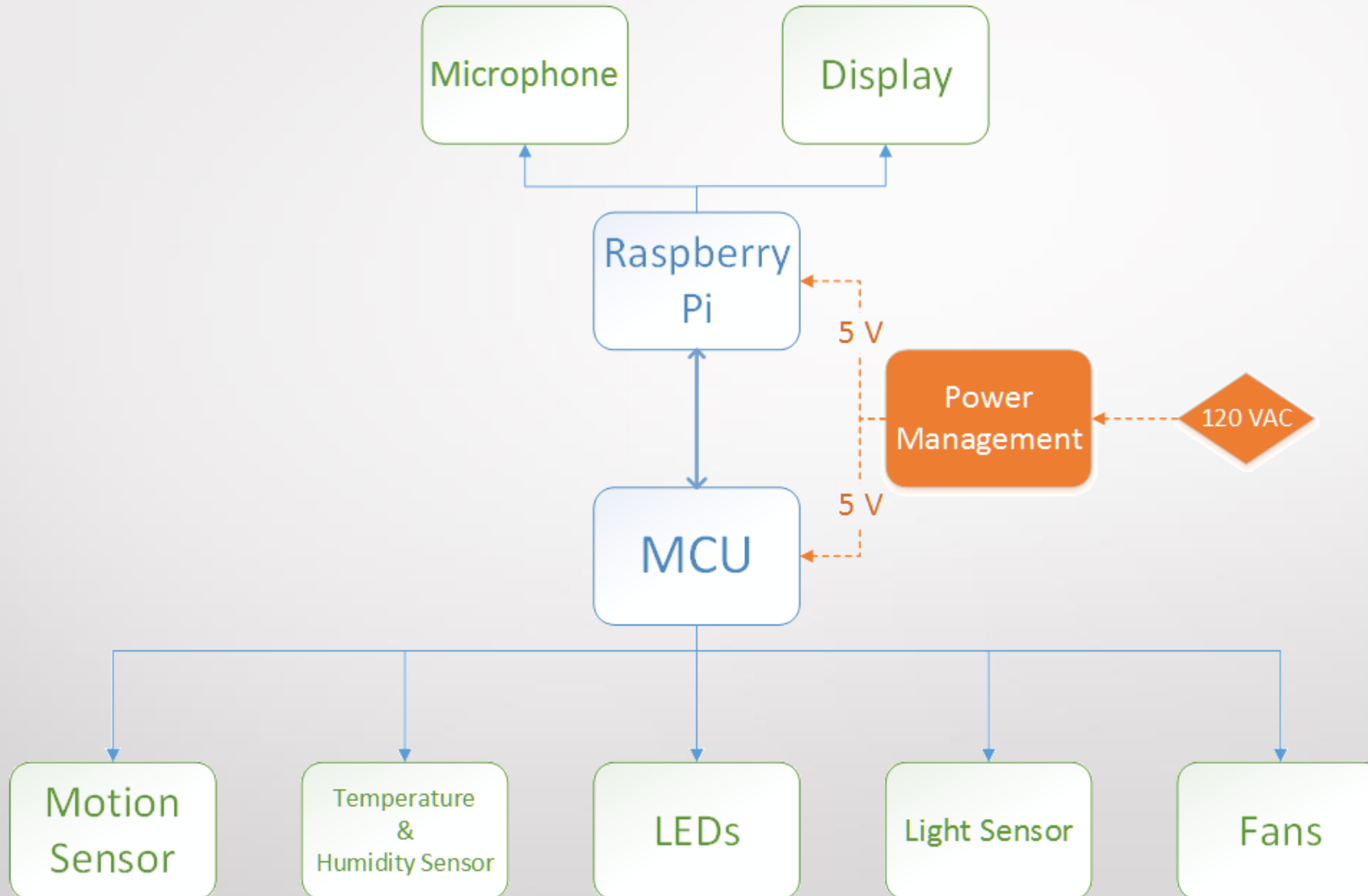
| Parameter | GP2Y0A02YKoF |
|--------------------------|--------------|
| Voltage Supply | -0.3 to 7V |
| Power Consumption | 40 mA |
| Output type | Analog |
| Output Voltage | +/- 0.3 VCC |
| Maximum Sensing Distance | 80cm |
| Operating Temperature | -10 to 60 C |
| Price | \$9.90 |



Other Hardware

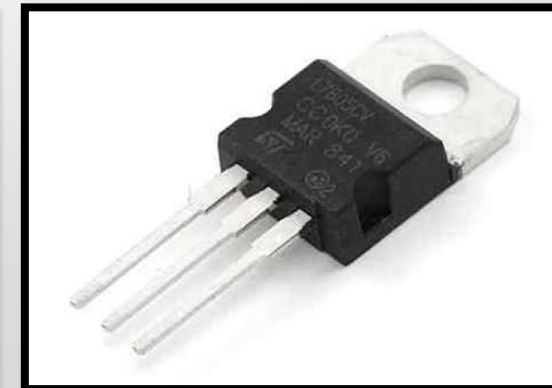
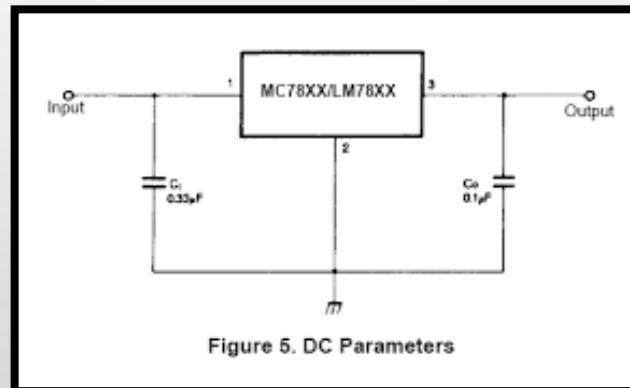
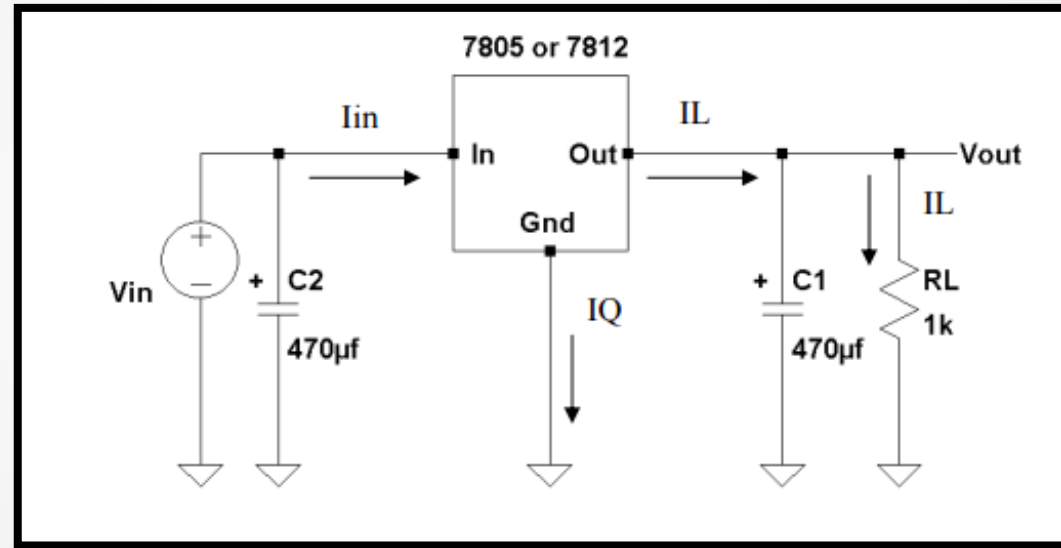
- Display Device
 - 32-inch television behind one-way mirror as earlier discussed
- Speakers
 - External speakers via 3.5mm audio out from Raspberry Pi
 - Internal speakers are present, pending update from Microsoft for audio over HDMI
- Microphone
 - Webcam mic – Logitech C920 Pro
- 3W LED on top of mirror for low-light scenarios

Power Control



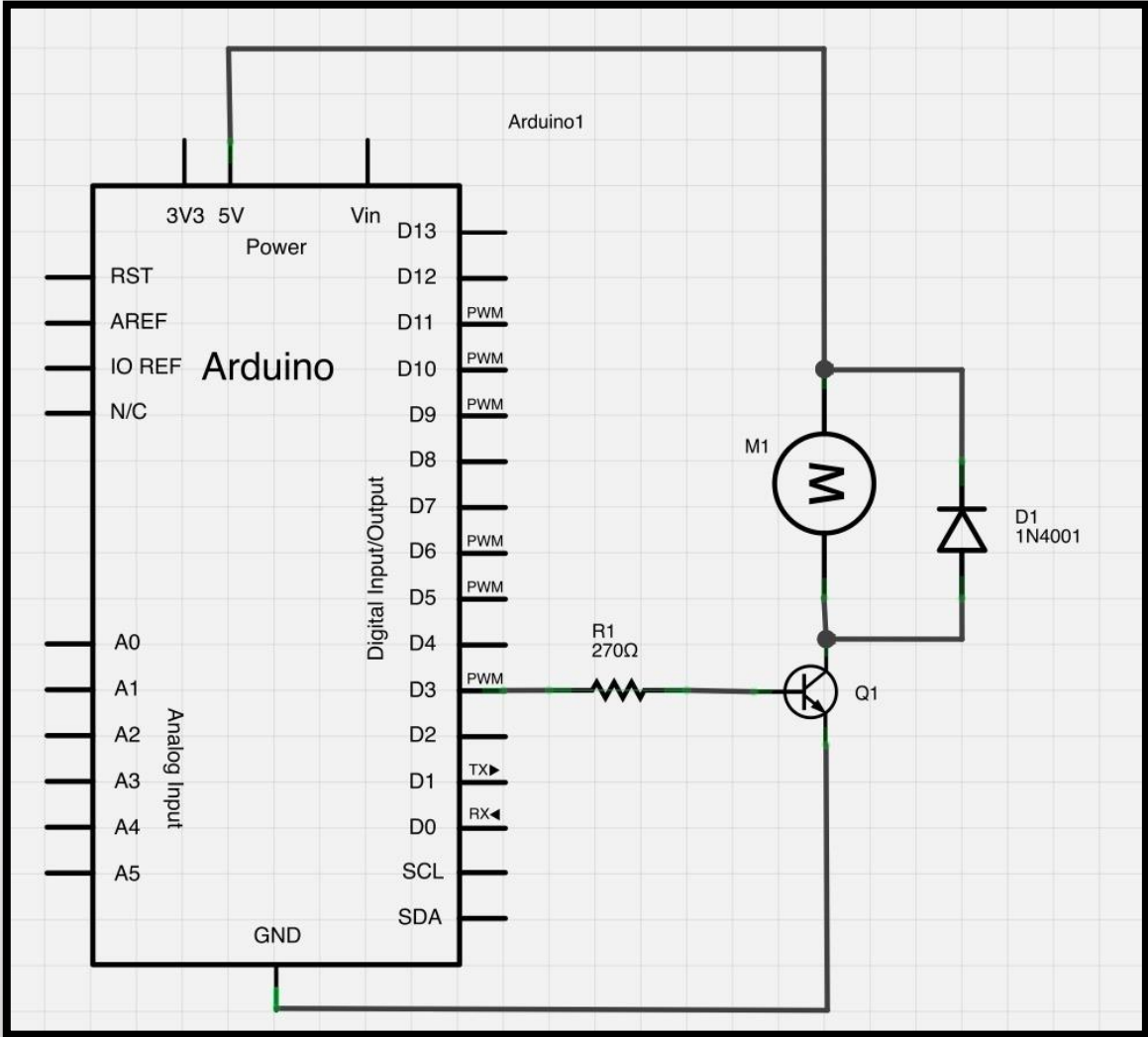
Linear Voltage Regulator

- Same as the ones used in Experiment #3 from EEL 4309 – Electronics II
- 12 V
- 5 V

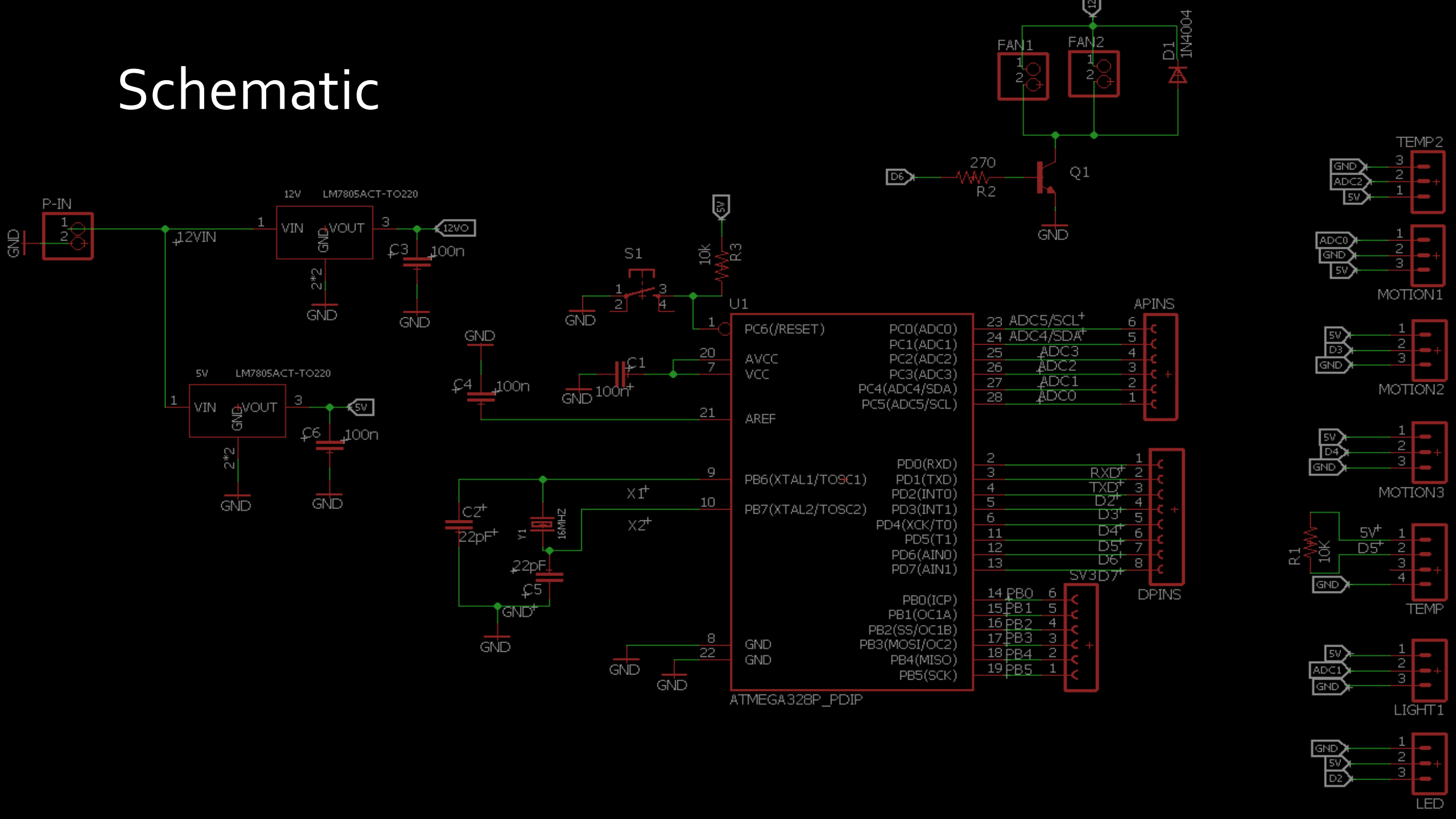


12V Fan Power

- MCU will send signal to the desired pin and complete the circuit that will activate the fans

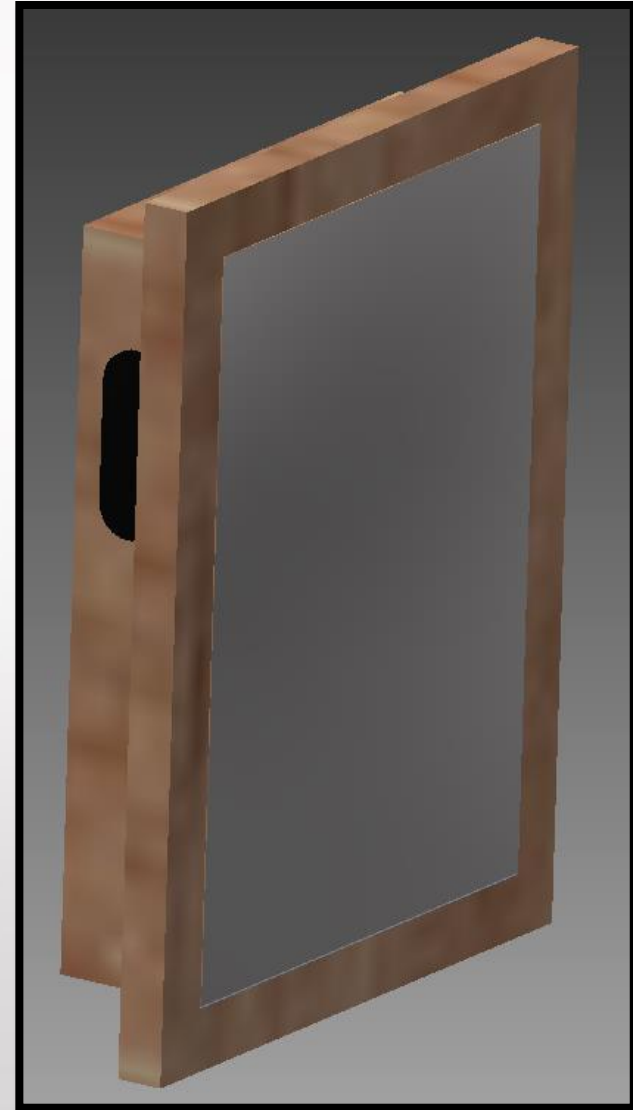


Schematic



Mirror Housing

- Stained Wooden Frame
 - Frame backed by sturdy housing
- One-Way Mirror In Front of TV
- Motion Sensor Mounted on Bottom
- Speakers on Sides
- Raspberry Pi USB access on Side
- Single LED Mounted on Bottom



Display Layout

- Offer information at all times
- Preserve mirror space
- Display important information closest to where your eyes fall
- Removable display elements for different use cases



Software Design

Considerations

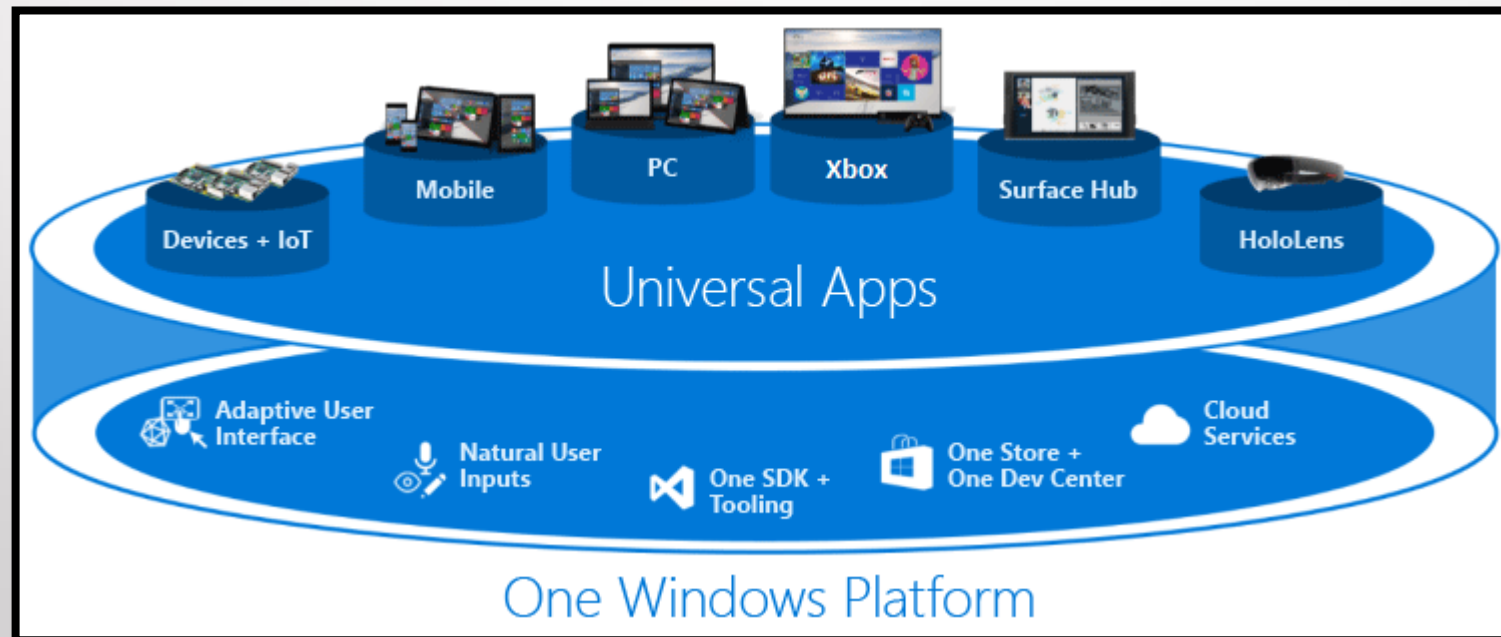
- Run on multiple platforms seamlessly
- Adaptable UI across platforms
- Modularity
 - For ease of creation with multiple developers
 - For future additional features

Results

- Universal Windows Platform
- Model-View-View Model Pattern

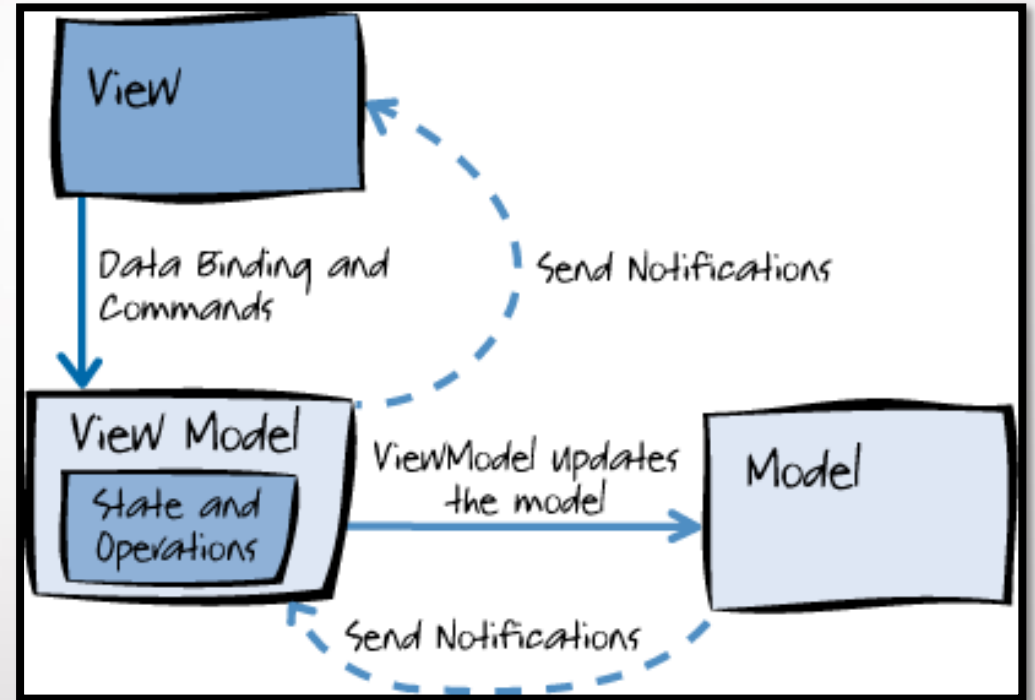
Universal Windows Platform (UWP)

- Standard Windows 10 runtime model
- GUI defined by XAML files using data binding for modularity
- Common API accessible by all Windows 10 devices
- Different API's accessible by individual platforms

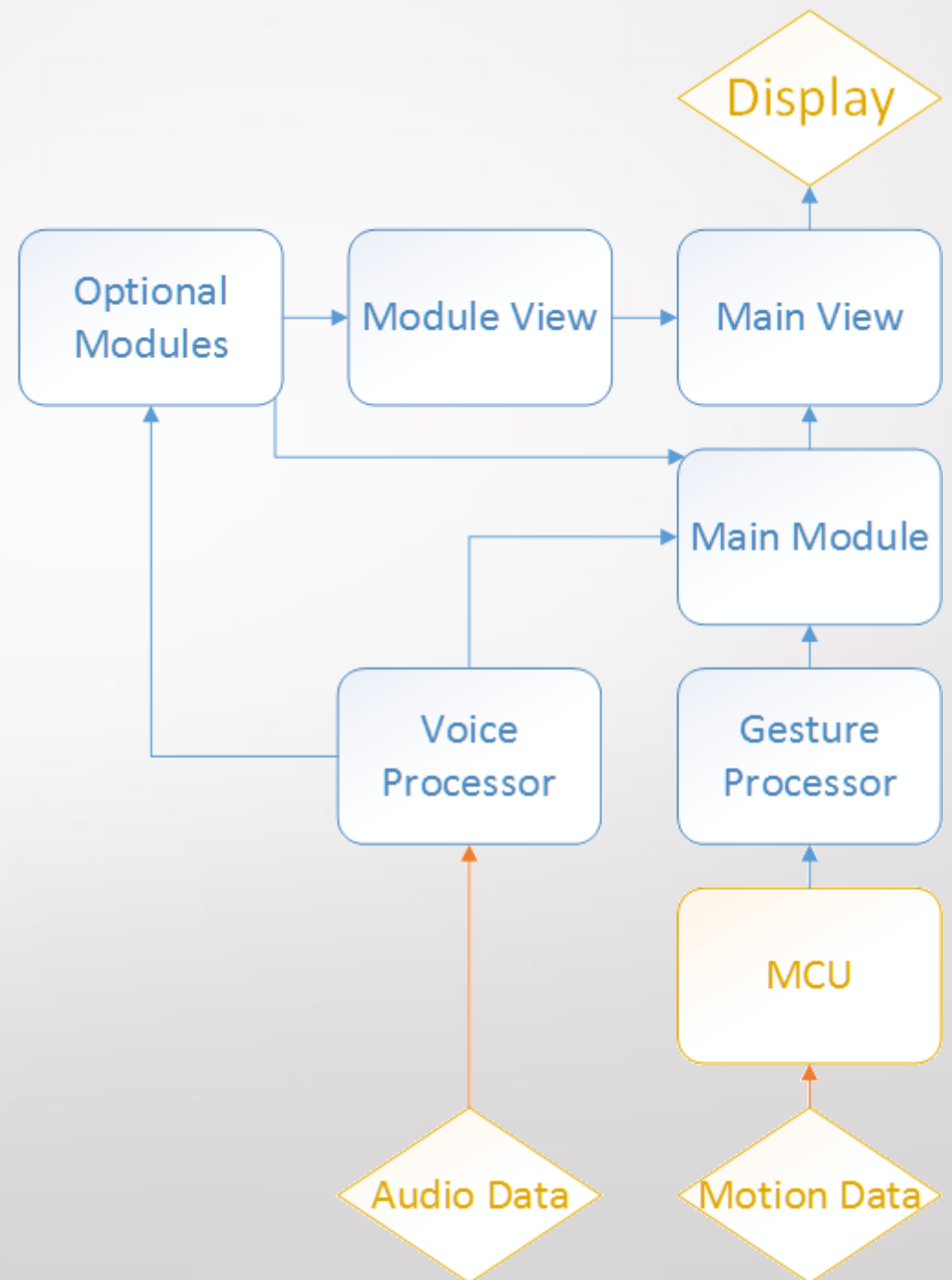


Model-View-View Model (MVVM)

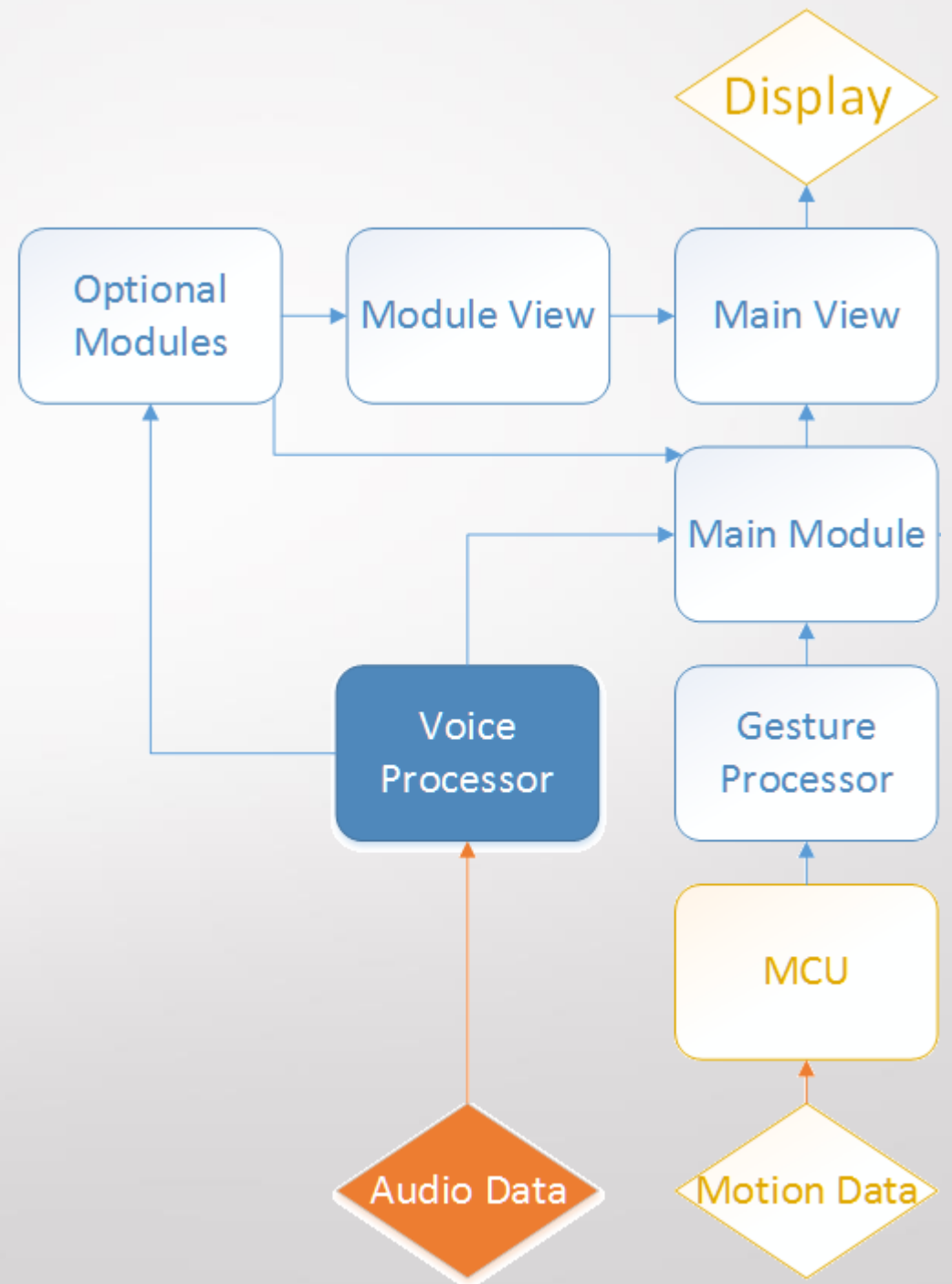
- Two reasons
 - Works great with UWP
 - Supports Modularity
- Loose coupling with Data Binding allows information to be seamlessly switched
- Easily format different data into similar layouts
- Easily create multiple GUI layouts from the same data bindings



Software Design



Voice Processor



Voice Processor Class Diagram

- Singleton Class
- Runs in separate thread
- Contains reference to all voice controlled modules
- Passes control to appropriate module when command received

Voice Processor

```
-Tags : List<String>
-ActiveModules : List<IVoiceControlModule>
-Recognizer : SpeechRecognizer
-----
+InitializeSpeechRecognizer() : void
+LoadModulesAndStartProcessor(List<IVoiceControlModule>) : void
+IsModuleLoaded(IVoiceControlModule) : boolean
+CreateGrammarFromFile(String, String) : SpeechGrammar
+UnloadSpeechRecognizer() : void
-RecognizerResultGenerated(SpeechSession, SpeechArgs)
```

1

Has

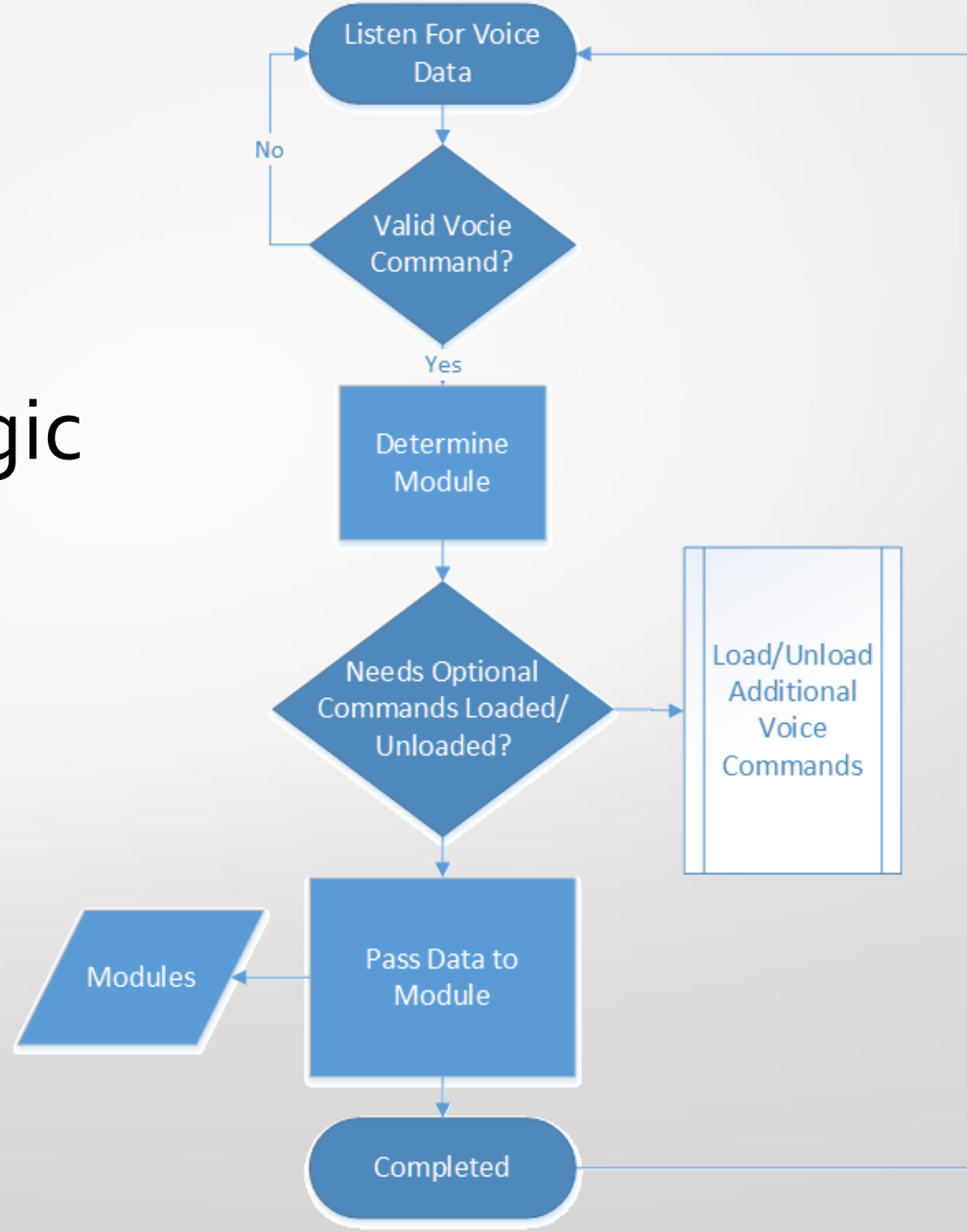
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<<Interface>>

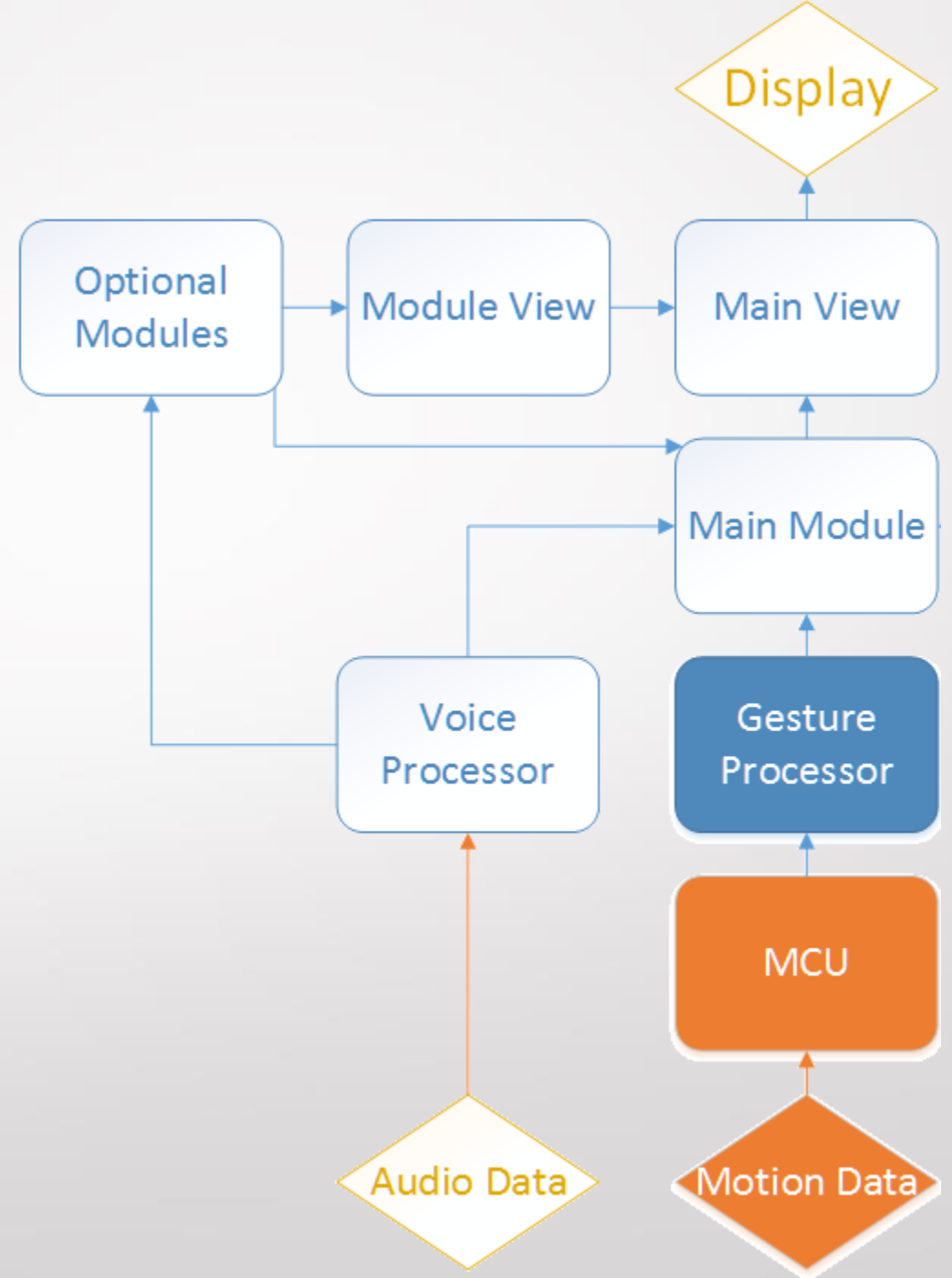
IVoiceControlModule

```
+IsVoiceControlLoaded : boolean
+IsVoiceControlEnabled : boolean
+VoiceControlKey : string
+GrammarFilePath : string
+SpeechRecognitionGrammar : string
-----
+ProcessVoiceCommand() : void
```

Voice Processor Logic



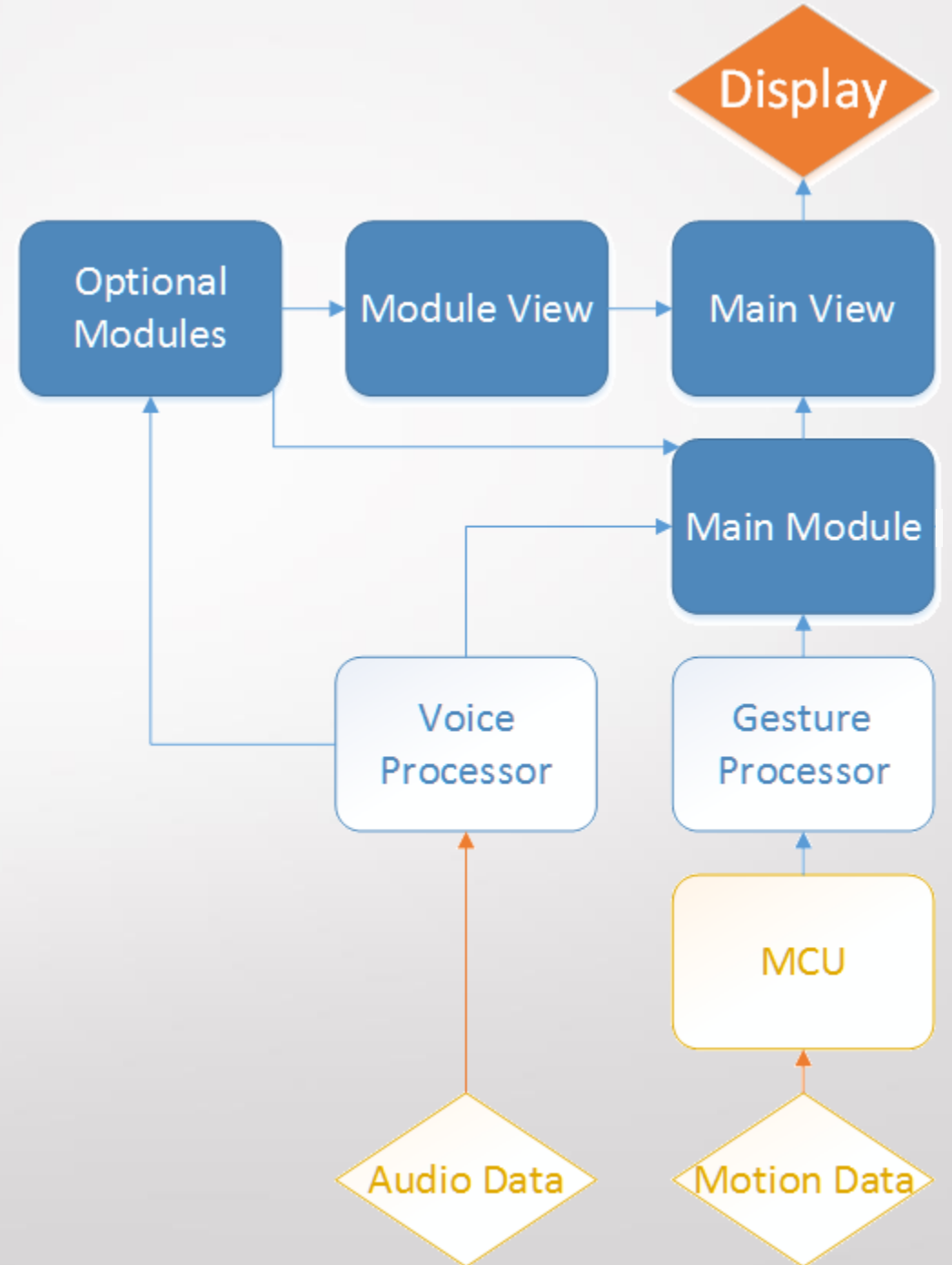
Gesture Controls



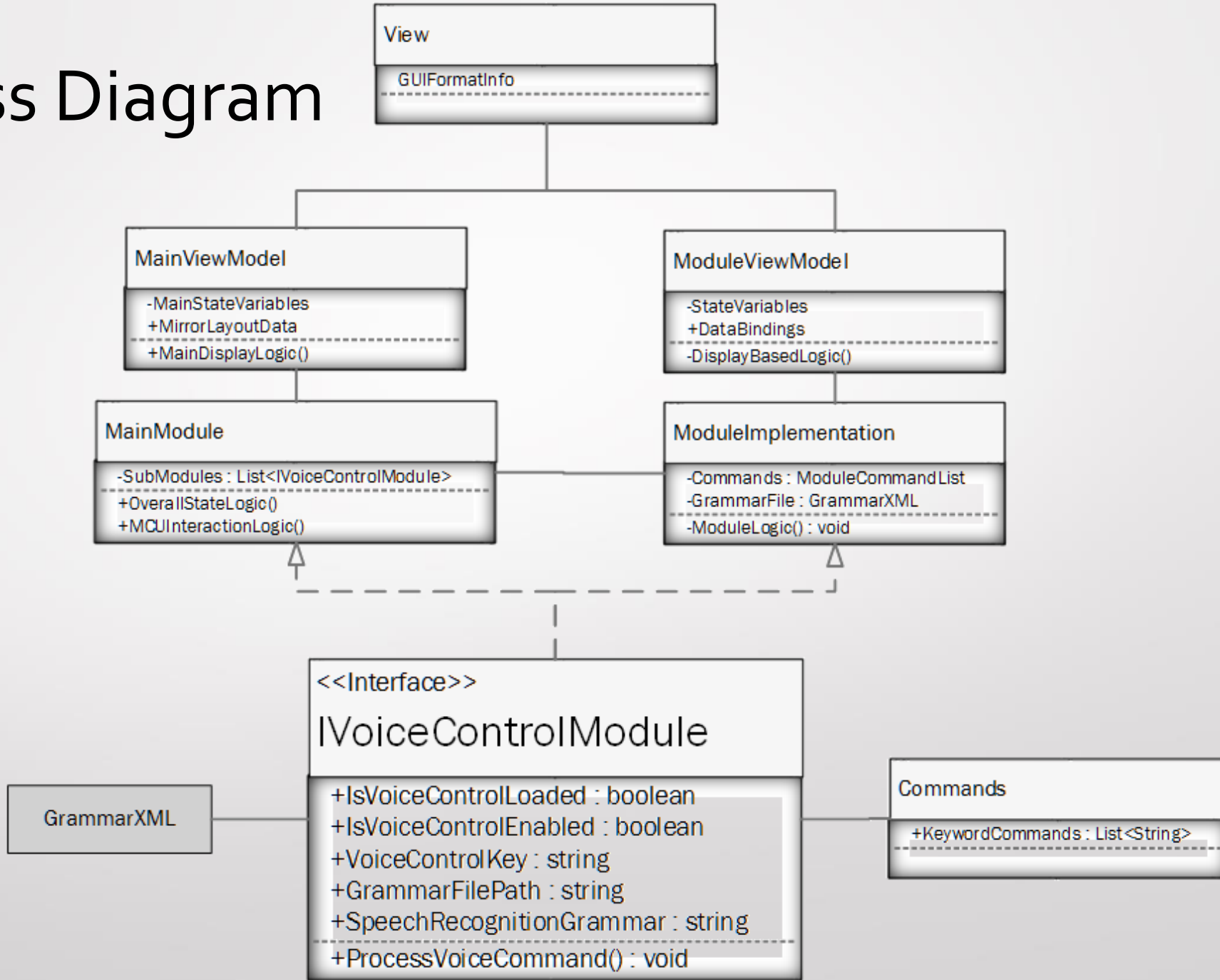
Gesture Controls

- Simple Gesture Controls
 - Use of the mirror itself
 - Hardware Limitations
 - Kinect: 3.1GHz Processor, USB 3.0, 4GB RAM
 - Leap Motion: 2GB RAM
- Uses
 - Initiate Music Playback
 - Next song
 - Stop Music

Software Modules



Module Class Diagram



Main Module

- Boot into Main Module on startup
 - Win10 IoT boot option
- Maintains a reference to all submodules for information exchange
- Handles all sensory information from MCU

Software Modules

- Clock
- Weather
- News
- Music
- Commute Time



Clock

- Digital Format
- Uses System Time
 - Raspberry Pi – Windows 10 IoT
 - NTP server
- Military 24-Hour Format
 - User setting

09:58



Weather

- OpenWeatherMap API
 - Returns JSON object
- Formats:
 - Current Weather
 - Today's Weather
 - 3 hour intervals – Highs and Lows & Icon
 - Tomorrow's Weather
 - 3 hour intervals – Highs and Lows & Icon
 - Week's Weather
 - 5-day forecast – Highs and Lows & Icon

Orlando, FL
Thurs, September 29

 76°
Hi: 79°
Low: 74°



News

- News Headlines
 - List of 4 Headlines
- CNN
 - RSS2JSON API
 - Returns JSON object
- Request different categories via Voice Command
 - Top News
 - Business
 - Technology
 - ...



Music

- Local Media
- Now Playing View
 - Artist – Song
- Music playback controlled with gestures
- Sound output to external speakers



Commute Time

- User sets location
 - Work | School



Commute Time

- User sets location
 - Work | School
- Google Maps
 - Distance Matrix API
 - Fetch travel time from current location



Configuration & Setup

- Initial User Setup
 - 24-Hour Clock Format
 - Work/School Locations
 - Time to leave for work/school



Administrative Content

Work Distribution

| Name | Embedded Hardware | Voice Recognition | Software Modules | Frame Design |
|------------------|-------------------|-------------------|------------------|--------------|
| Hector Zacarias | P | | | S |
| Justin Gentry | S | P | S | P |
| Michael Trivelli | | S | P | S |

Budget

| Item | Quantity | Cost |
|--------------------------------|----------|---------|
| MCU | 0 | \$0 |
| Power Relay | 1 | \$1.41 |
| Fan | 2 | \$20.48 |
| Diodes | 1 | \$0.32 |
| Proto Broad | 2 | \$0.76 |
| Motion Sensor (Long-Range) | 1 | \$1.80 |
| Motion Sensor (Short-Range) | 2 | \$9.90 |

| Item | Quantity | Cost |
|--------------------------|----------|----------|
| Humidity and Temp | 1 | \$1.75 |
| PCB | 10 | \$14.00 |
| 32-inch 1080p HDTV | 1 | \$100.00 |
| Raspberry Pi 2 Kit | 1 | \$114.95 |
| Microphone | 1 | \$0 |
| Speakers | 1 | \$0 |
| Mirror Assembly/Frame | 1 | \$104.25 |
| Total: | | \$369.62 |

Issues

- Motion/Light sensor
- False voice recognition
- Eagle learning curve



Questions