2-Cycle Power System

- •Group 37:
- Alexander Carpenter
- Brian Dunsmore
- Christian Cruz Paez
- Yonder Salomon

Motivation

Create Create a self-sustained green energy system Develop a remote-control system for power source Develop control Gain a better understanding of power generation Gain controls Lessen the need for large scaled power generation Lessen facilities

Goals and Objectives

Solar panel supply power to both internal and external loads and charger system.

Have the system switch between voltage sources

Wireless transmission of system data

Power Information PCB Solar panels design Power out control system Relay LCD Data information display Alex Carpenter Power Temperature Data Power out Brian Power Dunsmore Voltage Power out Information on loads Microcontroller regulator Christian Power Cruz Paez Power out Data Flow rate Yonder sensor Salomon Control Micro system Power out Battery Water pump hydroelectric system system DC power Battery DC power Power Load and AC power charge inverter outputs Power regulator

Overall block diagram

Specifications

#	
1.0	The system shall have the ability to generate 20 watts of power from solar panels.
1.1	The system shall have the ability to pump at least 240 gallons per hour from the micro hydro-generator.
1.2	The system shall have the ability to charge a 7 amp-hour battery.
1.3	The system shall have the ability to control when the solar panel and the hydro-generator are operated.
1.4	The system shall be able to be remotely operated at a range of 25 meters.
1.5	The system shall conform to applicable safety standards.
1.6	The system shall have the ability to switch between generating power from solar panels and the hydrogenerator within 5 minutes.
1.7	The system shall have the ability to engage both power generation sources simultaneously at a predetermined load power threshold (6 Watts).
1.8	The system shall be able to be implemented into pre-existing households within 2 hours.
1.9	The sensor's measuring power shall remain accurate within 0.2 Watts.

Solar Panels

Topsolar

20-watt output

2.32 x 13.86 x 17.13 inches

The panel comes with the ability to adjust the angle to any degree needed for power generation

Initial panel testing done with a program pv-watts

Brand	Wattage	Efficiency rating	Voltage load	Installation
Sunsol	20 Watts	23 % rating	12 volts	Easy, with a 180- degree adjustable
Top solar	20 Watts	24 % rating	12 volts	Easy, with a 180- degree adjustable
Sunmind	3.5 Watts	18 % rating	12 volts	Fixed position, no installation needed

Panel comparison

Water pump

Brand	Voltage	Gallons per Hour	Power draw	Size
Echpow	12 Volts	63	4.2 Watts	51mm x 34mm x 42.7mm
AEO	12 Volts	240	5 Watts	5" x 2.28" x 3.54"
GENEDEY	12 Volts	210	19 Watts	77mm x 63mm x 49mm



Brand	Voltage	Charge current	Power	Noise
Pmasanzy	0-80 Volts	.22 Amps	10 Watts	55 dB
Savemore	12 Volts	.133 Amps	10 Watts	55 dB
Dinctery	12 Volts	.22 Amps	10 Watts	55 dB

Hydro Generators

Battery comparison

	Lithium-ion	Nickel Metal Hydride	Lead Acid	Zinc-ion	
Capacity	3.3 Ah	11 Ah	7.7 Ah	7 Ah	
Life Cycles	1000	1000	500	15000	
Battery Size	attery Size 12 volt 12 volt		12 volt	12 volt	
Discharge	.65 Amps	.55 Amps	.66 Amps	.65 Amp	
Power type	Lithium graphite	Nickel Hydride	Sealed lead acid	Zinc manganese	
Price	\$300	\$24	\$20	\$50	

Solar charge controller

Charge controllers are essential for safety

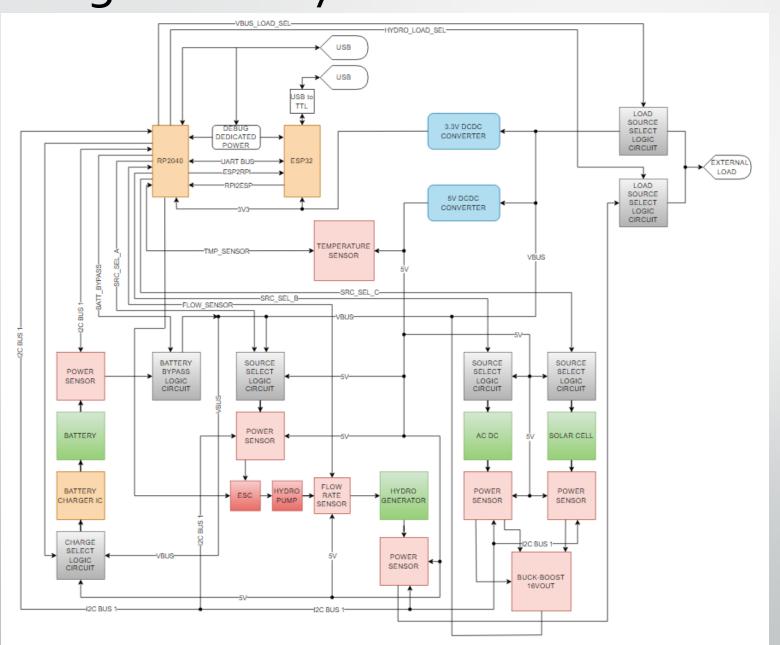
Charge controllers help charge more efficiently

Gives us accurate data to pull from

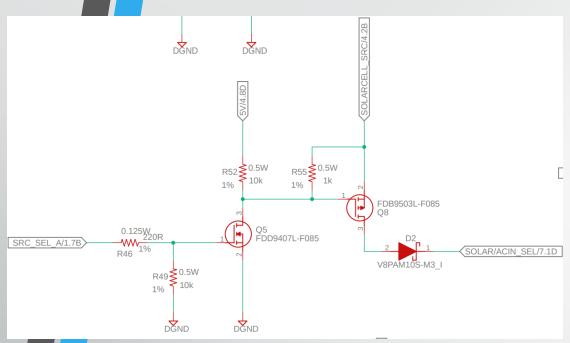
MODEL	KLD1210 KLD1220		20	KLD1230	KL	D4820	KLD4830
Batt voltage	12V/24V auto			48V			
Charge current	10A 20A			30A 20)A	30A
Discharge current	10A 20A		30A	20A		30A	
Max Solar input	<50V				<80V		
Fauclization	B01 sealed		BO	B02 Gel		B03 flood	
Equalization	14. 4V		14. 2V		14. 6V		
Float charge	13.7V(defaul,adjustable)						
Discharge stop	10.7V(defaul,adjustable)						
Discharge reconnect	12.6V(defaul,adjustable)						
USB output	5V/3A						
Self-consume	<10mA						
Operating temperature	-35~+60 °C						
Size/Weight	150*78*35mm /150g						



High Level System Architecture



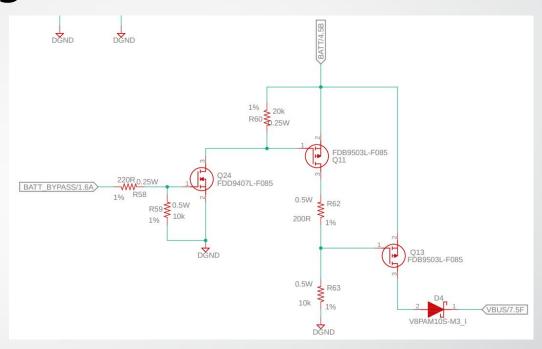
FET Based Logic Circuits



Used to gate the input sources, software controlled.

Based on NMOS-PMOS combinational logic using Logic Level featuring low Rds on for minimal thermal loss.

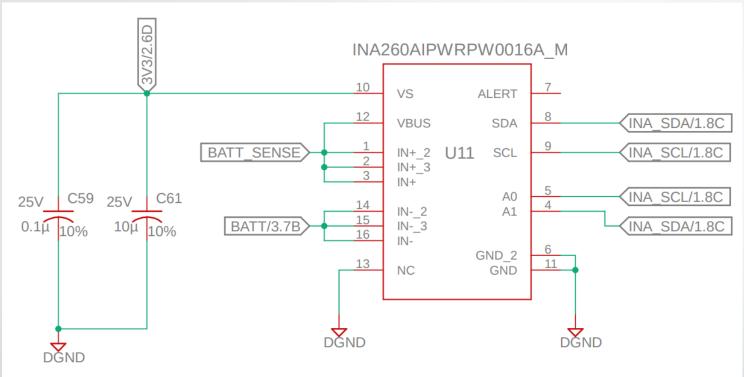




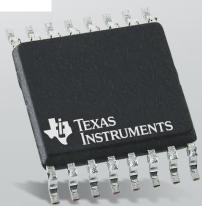
- Battery Bypass Circuit.
- Used to deviate all of the system load from the battery when charging operations are in progress.

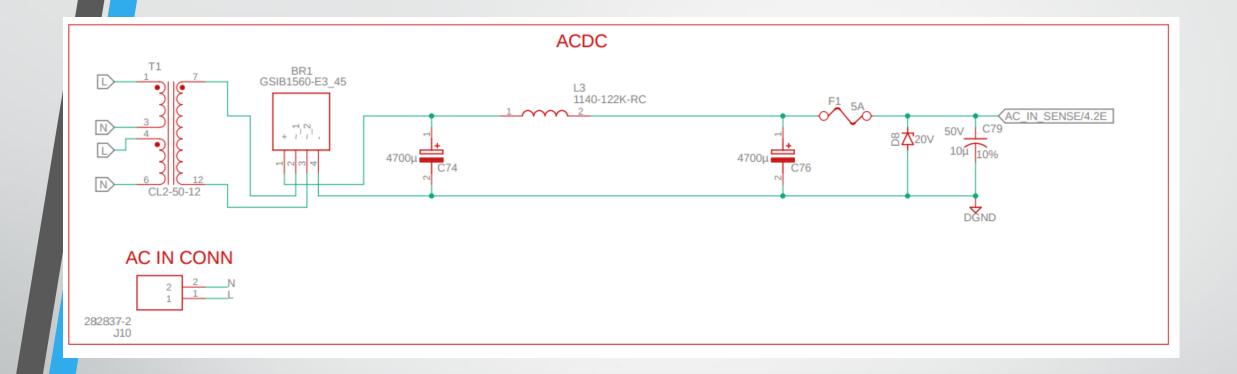


Power Sensing



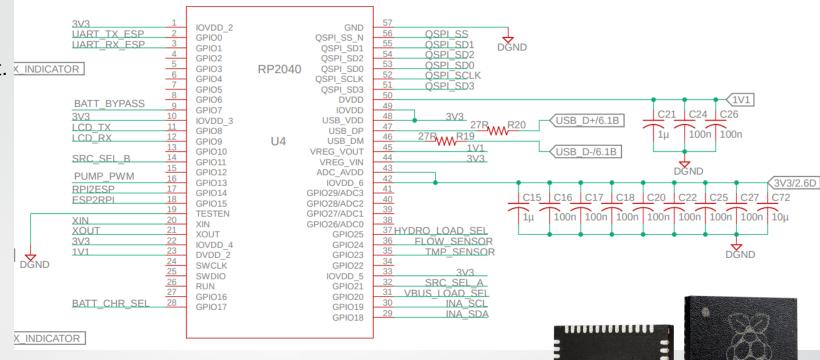
- TI's INA260
- Power sensor able to measure up to 15A @ 36V.
- Telemetry data transmitted via I2C

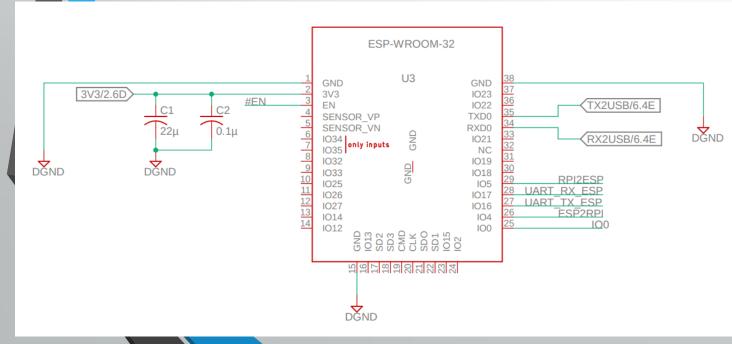




- AC to DC rectification and power conditioning
- Featuring a Pi Filter to maximize ripple reduction

- Raspberry Pi's RP2040 Main processing unit. INDICATOR
- ESP₃₂ as coprocessor and Wireless Communications Module.
- UART bus for Inter Board Communications.
- Interrupt lines for seamless and reliable communication link.

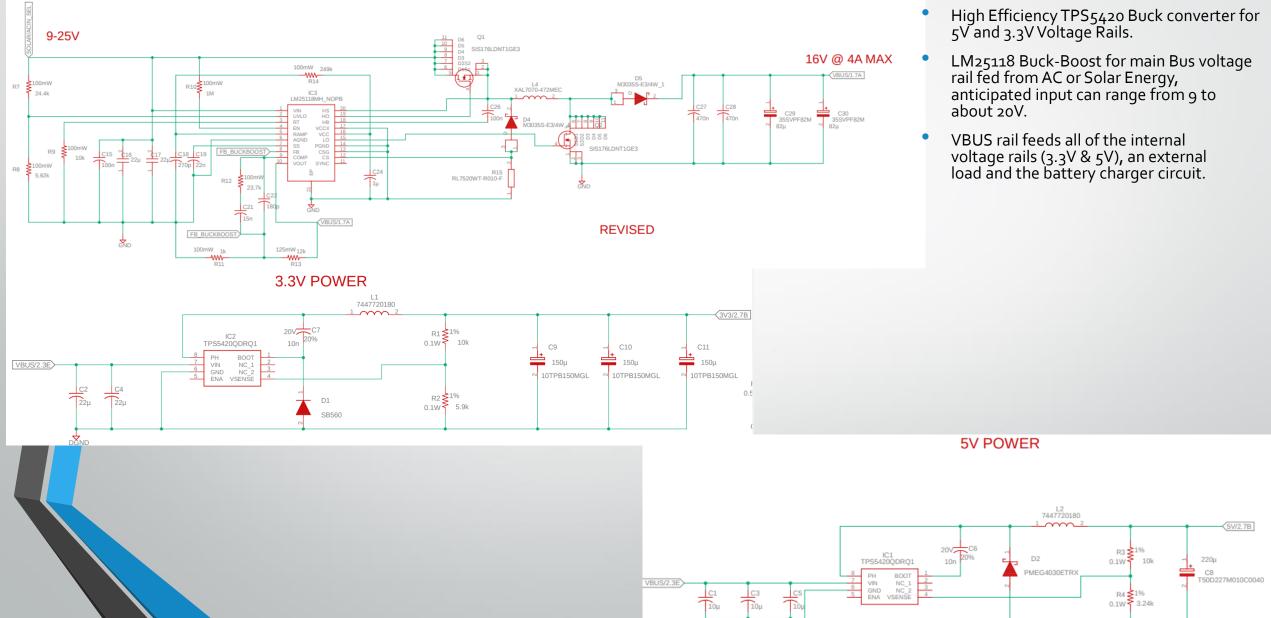


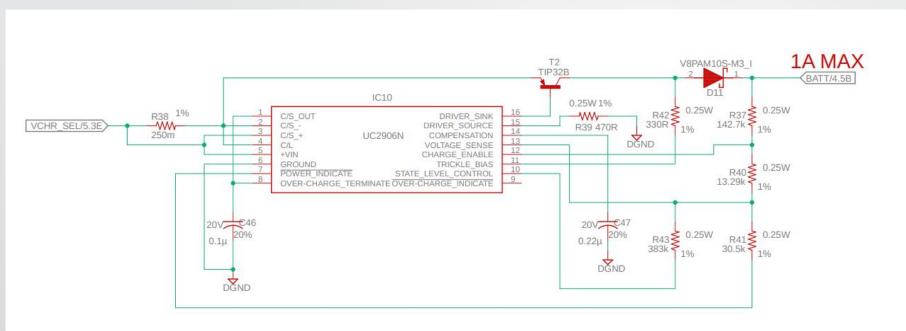


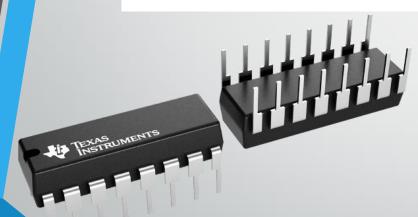


11111111111111

Power Stages

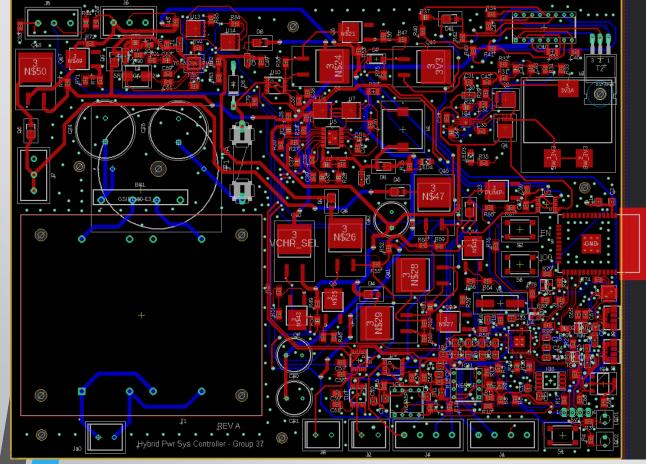


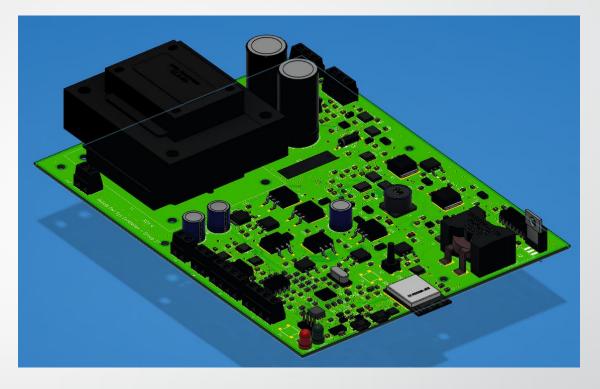




- Battery Charger IC
- Highly Reliable Resistor Configurable
- Charge Current merely dependent on T2 characteristics
- Charging current limited to 1A for a 7.2Ah Battery (C/7).

PCB Layout & 3D Model





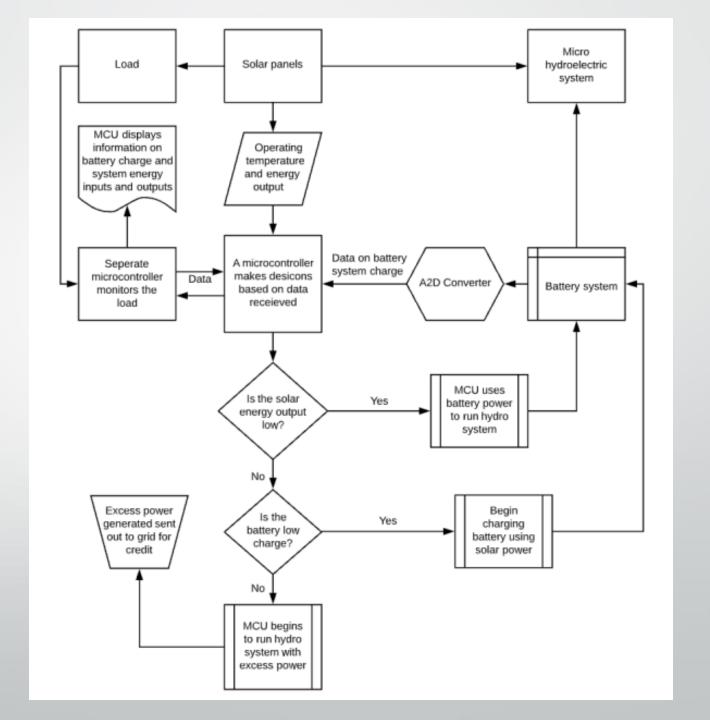
- 4 Layer Board Layer Stackup:
 - -Ground / Signals
 - -Ground
 - -3v3 Net
 - -Ground / Signals

Software Development Language

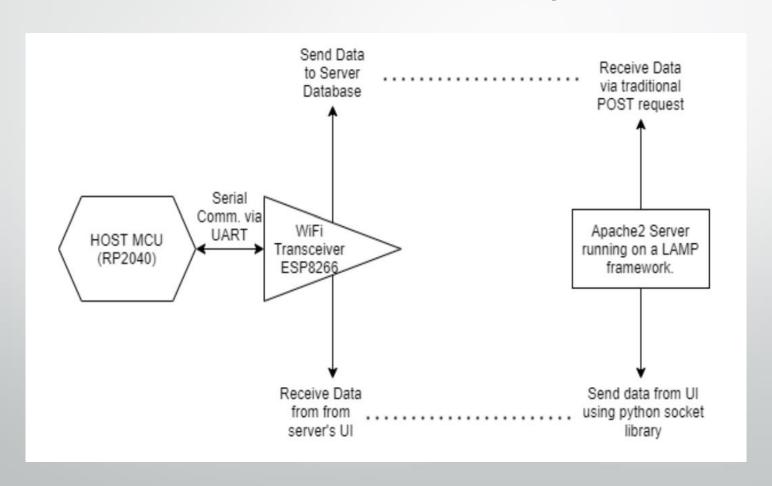
- Micropython:
 - High-Level language
 - Exception error handling
 - Existing Libraries for Power/voltage sensors and water-flow sensors
 - Cheap/energy efficient Microcontrollers



Software Flowchart

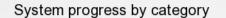


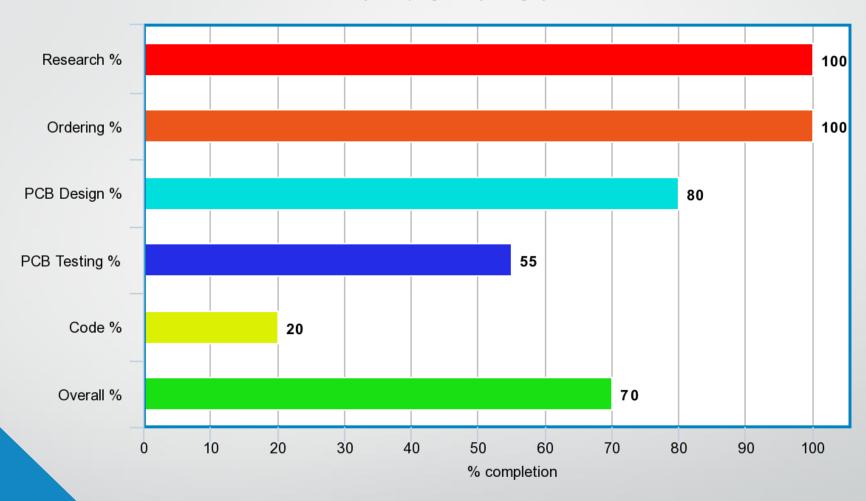
Wireless Transmission of System Data



Total projected costs

Part	Cost
Raspberry Pi Pico (RP2040)	
Solar panels	
Submersible water pumps	
Battery bank	
Battery charge regulator	
LCD Display	
РСВ	
PCB Components	
All sensors	
Additional components	
Total Parts cost	~\$600





Current project progress



Project challenges

Initially developed PCB with lithium-ion compatible chip

Attempted to cook PCB in UCF reflow oven to no avail

Code structuring has been slow to start

Current project estimates

PCB fully tested by Februrary 26th

System platform and enclosures completed by March 6th

Software completion by March 13th

System integration and testing by March 27th

Final system testing performed by April 1st