

# **ASLBoT**

#### Assisted Sign Language Bot Translator

Group #14

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Assigned Professor

Dr. Samuel Richie

Advisor/Client

Dr. Chung Yong Chan

### **Motivation**

- Member works at a clinic
  - Noticed a lack of efficient translation
  - Looking for standardized language interpretation
  - No support for sign language
- Classroom Setting
  - Interpretation Services are not adequate
  - Use of ASL Translators is expensive

### **Motivation (cont.)**

- No current marketable product
  - Sign language machine translation still in research phase
  - No open-source large corpora for English to ASL
  - No standardized training framework

### **Goals & Objectives**

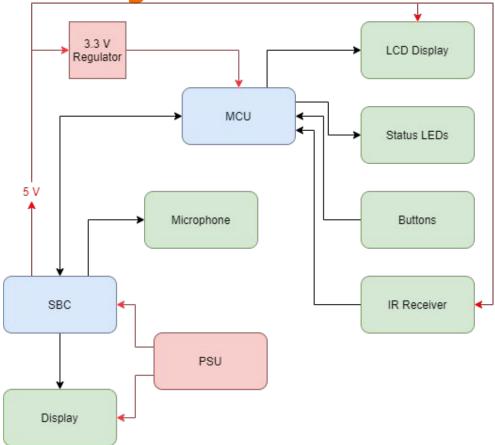
- Translate English speech into American Sign Language.
- Use small corpora to achieve ASL translations using a training framework
- Perform speech-to-text and speech-to-ASL language translations.
- Indicate various statuses of the device via LEDs.
- Capture audio at frequencies around natural human pitches that can be translated into text via speech-to-text algorithms.
- Display responsive high-quality animations of sign language gestures.
- Receive manual inputs from the user such as start/stop recording.

### **Requirement Specifications**

Component	Parameter	Design Specification
Microphone	Frequency Response	300 Hz to 3kHz
Memory	Size	32 GB
Power Supply	Power	32 W
System	Translation Accuracy	20% (BLEU Average)
System	Cost	\$500
System	Response	< 5 seconds
Vocabulary	Model Complexity	> 50 words
Neural Machine Translation	Size	< 1000 Entries

### **Hardware Components**

### **Overall Block Diagram**



### **MCU Selection**

	GPIO Pins	ADCs	Communication Protocols	Cost
STM32L162ZDT6	115	12-bit/ 40 Channels	I <sup>2</sup> C, I <sup>2</sup> S, SPI, USART, USB	\$9.80
STM32L151RDT6TR	51	12-bit/ 40 channels	I <sup>2</sup> C, I <sup>2</sup> S, SPI, USART, USB	\$6.85
MSP430FR6922	46	12-bit/ 8 channels	I <sup>2</sup> C, SPI, UART	\$5.33
MSP430FR6989	83	12-bit/ 16 channels	I <sup>2</sup> C, SPI, UART	\$7.86

### **MCU Development Environment**

#### Energia

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* Interfacing 16*2 LCD with MSP430G2553 in 4-bit mode using	Energ	ia	
*/ #define RS 3			
#define EN 2			
#define D4 4			
#define D5 5			
#define D6 6			
#define D7 7			
#include <liquidcrystal.h> //This librarey is insatlled by d</liquidcrystal.h>			
LiquidCrystal lcd(RS, EN, D4, D5, D6, D7); //Let the librare	y know	how we	hav
void setup() (			
<pre>lcd.begin(16, 2); //We are using a 16*2 LCD display lcd.setCursor (0,0); //Place the cursor at 1st row 1st col</pre>			
<pre>icd.settursor (0,0); //Place the cursor at 1st row 1st col lcd.print("MSP430G2553"); //Display a intro message</pre>	umn		
<pre>icd.print("MSP430G2555"); //Display a incro message icd.setCursor(0, 1); // set the cursor to ist column 2nd</pre>	rou		
<pre>lcd.pctculsor(0, 1); // set the culsor to ist column int lcd.print("-CircuitDigest"); //Display a intro message</pre>	LOW		
delay(2000); //Wait for display to show info			
<pre>lcd.clear(); //Then clean it</pre>			
3			
<pre>int test =1;</pre>			
<pre>void loop() (</pre>			
<pre>lcd.print("LCD with MSP"); //Display a intro message</pre>			
<pre>lcd.setCursor(0, 1); // set the cursor to column 0, line</pre>	1		
<pre>lcd.print(test); //Display a intro message</pre>			```
<b>x</b>			
Board at COM3 is not available	Cop	oy error m	essages
Board at COM3 is not available			
1 MSP-EXP430G2 w	MSP430	32553 on (	COM3

#### Code Composer Studio

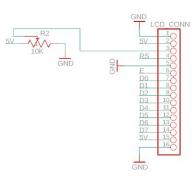
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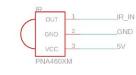
### **MCU Functionality**

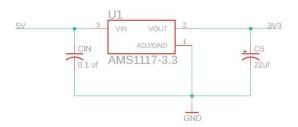


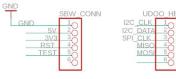
- Uses LEDs to indicate overall status of system
- Utilizes LCD to indicate recording status
- Communicates with SBC to send control signal and receive updates
- IR sensor for wake functionality
- On-board buttons to start and stop recording and reset

### Hardware Diagram

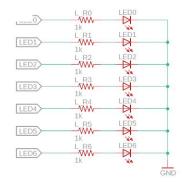


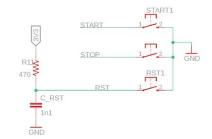


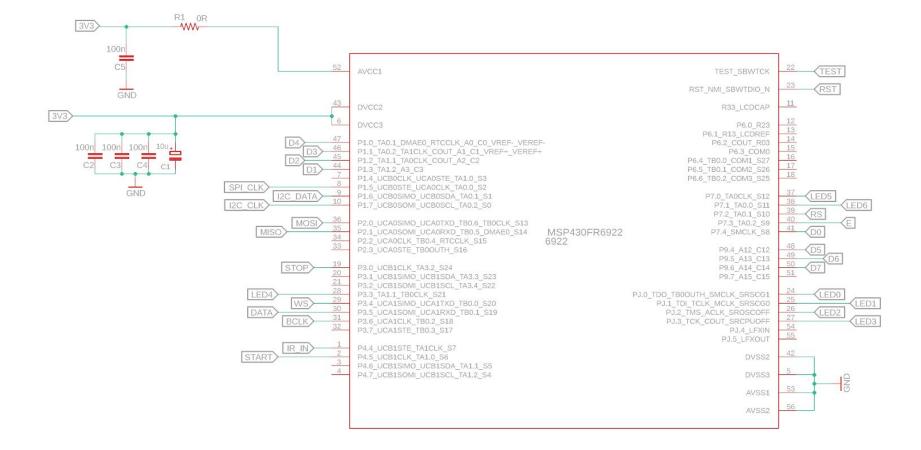




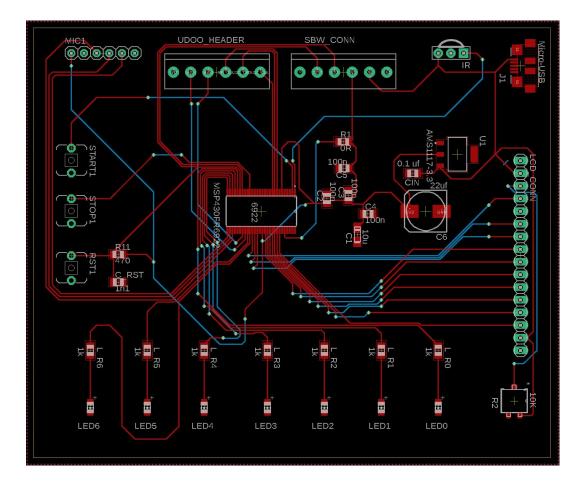












### **Microphone Selection**

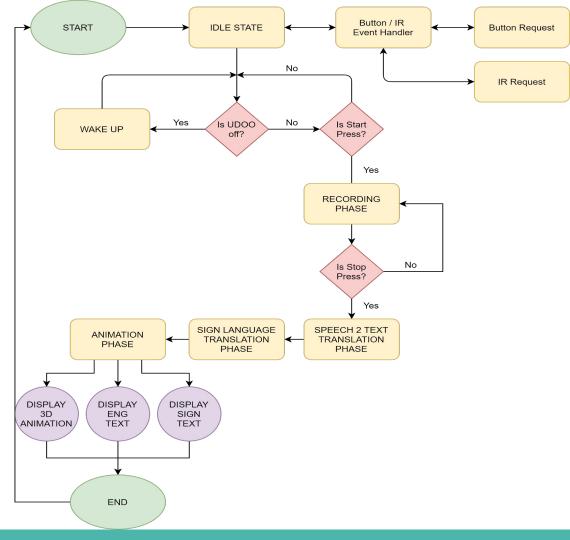
	Frequency Range	Output	Interface	Cost
Mini USB Microphone	100 Hz - 10 kHz	Digital	USB	\$4.95
SparkFun MEMS Microphone (INMP401/ADMP401)	100Hz - 15 kHz	Analog	ADC	\$10.95
MEMS Microphone (SPH0645LM4H)	50 Hz - 15 kHz	Digital	l <sup>2</sup> S	\$6.95
Blue Snowball	40Hz to 18kHz	Digital	USB	\$49.99

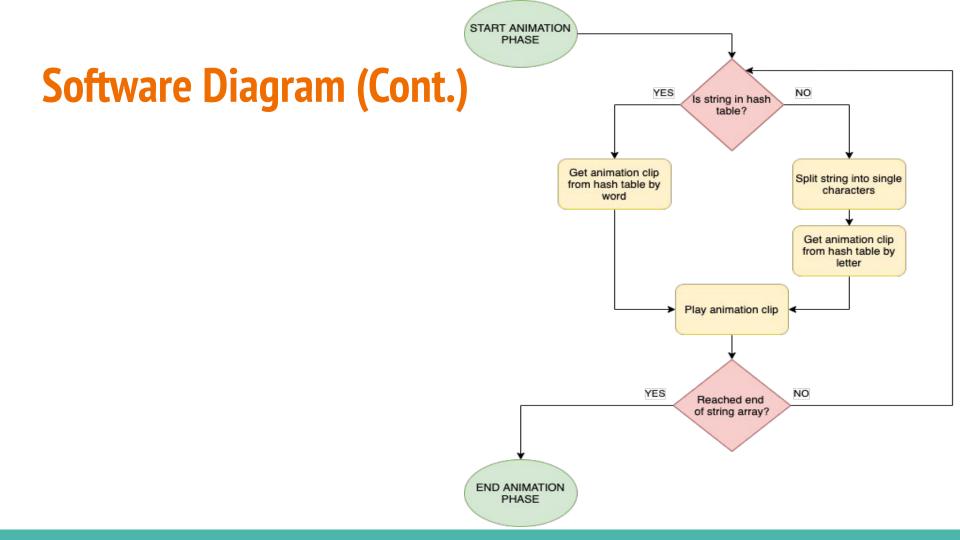
### **SBC Selection**

	Architecture	Communica tion Protocols	OS	RAM	Memory	Cost
NVIDIA Jetson Nano	ARM64	I <sup>2</sup> C, SPI, UART	Linux	4 GB	External Only	\$99.00
ASUS TinkerBoard	ARM64	I <sup>2</sup> C, SPI, UART, I <sup>2</sup> S	Linux	2 GB	External Only	\$70.00
UDOO x86 Advanced Plus	x86_64	I <sup>2</sup> C, SPI, UART	Linux Windows	4 GB	32 GB	\$176.00

### **Software Components**

### **Software Diagram**





### **Machine Translations**

### **Machine Translation**

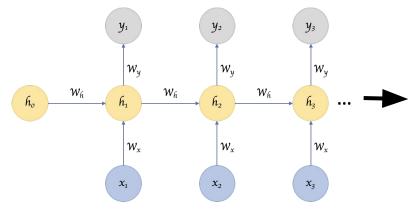
Rule-Based MT	Statistical MT	Neural MT
(RBMT)	(SMT)	(NMT)
<ul> <li>Large database of linguistic rules and millions of bilingual dictionaries.</li> <li>For the use of RBMT in text to ASL text translation, a massive database with the rules and resources will need to be created.</li> </ul>	<ul> <li>Statistical models that have parameters based on the analysis of monolingual and bilingual corpora.</li> <li>Relies heavily on existing corpora, minimum of 2 million words.</li> <li>CPU-intensive</li> </ul>	<ul> <li>Uses neural networks with training sets to tune weights.</li> <li>Examines entire sentence before translating, maintains the context of the sentence.</li> <li>Training requires GPU</li> <li>Large Training sets</li> </ul>

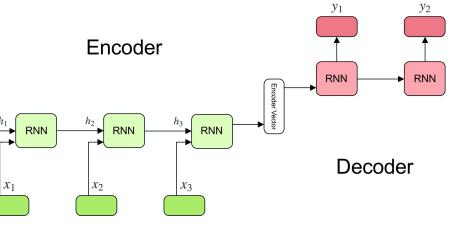
### **OpenNMT**

Open source and user support lacked in other systems	Provides Pytorch implementation	Based on seq2seq models that allow robust translation	
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**Recurrent Neural Network** 







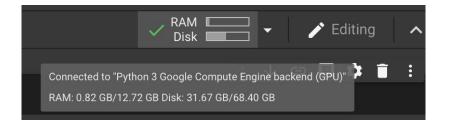
RNNshttps://towardsdatascience.com/recurrent-neural-networks-d4642c9bc7ce Seq-seq https://towardsdatascience.com/understanding-encoder-decoder-sequence-to-sequence-model-679e04af4346



**NMT Issue** Requires GPU for training

#### Google Colaboratory (Colab)

- Allows users to write and execute Python code on google's servers
- Free available GPU for processing
- Zero Configuration required





### **Training OpenNMT**

#### **Requirements:**

- Source (English)
- Target (Sign language Gloss)
- Source Validation
- Target Validation

Source	Target	Source Validation	Target Validation
I know sign language	ME KNOW SIGN	I want to know sign language	ME WANT KNOW SIGN LANGUAGE

### **Training OpenNMT - Issue**

**NMT Issue** Requires large Corpora

#### Two approach system:

- Specific Domain
- Redundancy

# **Training OpenNMT - Approach 1**

#### **Approach #1 Specific Domain:**

- Limits variety of words used
- Corpora based on daily school

hurry we need to go now on campus I need to write this paper tonight this project is due tomorrow my lecture starts in five minutes I am going to college this semester what classes are you taking I took that class last semester I wanted to go to the student union did you finish the paper last night I was absent from class yesterday Was the homework supposed to be done individually I am making new friends in college I made a friend yesterday Do you want to be friends there are a few ways to get to that building why is the campus so large the engineering building is very big I need help because I can not find this classroom I can't find this classroom I need help making these signs How many buildings are there on campus How much did you write for the paper

### **Training OpenNMT - Approach 1 Results**

- Improvement in translations
- Still very limited translations

SENT 1: ['where', 'can', 'I', 'find', 'the', 'classroom', 'building']
PRED 1: ME NEED HELP MAKE SIGN SIGN
PRED SCORE: -0.0293

SENT 1: ['I', 'need', 'help', 'finding', 'the', 'classroom']
PRED 1: ME NEED HELP MAKE SIGN SIGN
PRED SCORE: -0.0002

### **Training OpenNMT - Approach 2**

#### **Approach #2 Specific Domain + Redundancy:**

- Continue to limit variety of words used
- Breakdown existing sentences
- Introduce similar sentences

the engineering building is big

the engineering building

engineering building

building is big

engineering building is big

when did you finish your homework when did you finish did you finish your homework

finish your homework

### **Training OpenNMT - Approach 2 Results**

#### Model now better suited to translate English to Gloss

SENT 1: ['where', 'can', 'I', 'find', 'the', 'classroom', 'b PRED 1: ME NEED HELP MAKE SIGN SIGN PRED SCORE: -0.0293	First approach
SENT 1: ['where', 'can', 'I', 'find', 'the', 'classroom', 'b PRED 1: WHERE ME CAN FIND CLASSROOM PRED SCORE: -0.0006	+Second approach
SENT 1: ['I', 'do', 'understand', 'the', 'homework'] PRED 1: ME NOT WANT KNOW PRED SCORE: -0.2670	First approach
SENT 1: ['I', 'do', 'understand', 'the', 'homework'] PRED 1: ME UNDERSTAND HOMEWORK PRED SCORE: -0.0006	+Second approach

### **Training OpenNMT - Approach 2 Results**

The model may still struggle with some translations:

SENT 1: ['I', 'want', 'to', 'make', 'friends', 'this', 'semester'] PRED 1: ME WANT MAKE FRIEND AT COLLEGE PRED SCORE: -0.0245

SENT 1: ['I', 'need', 'help', 'with', 'the', 'homework', 'because', 'it', 'is', 'difficult']
PRED 1: ME NEED HELP BECAUSE CANNOT FIND CLASSROOM
PRED SCORE: -0.0050

### **BLEU Score**

#### **Benefits:**

- Quick calculation
- Simple score calculation
- Language does not matter
- Widely adopted (documentation available)

#### **Problems:**

- Shorter sentences (even if accurate) get close to zero scores
- Score changes depending on the reference file

#### BLEU = 13.81 62.0/30.2/14.1/1.6

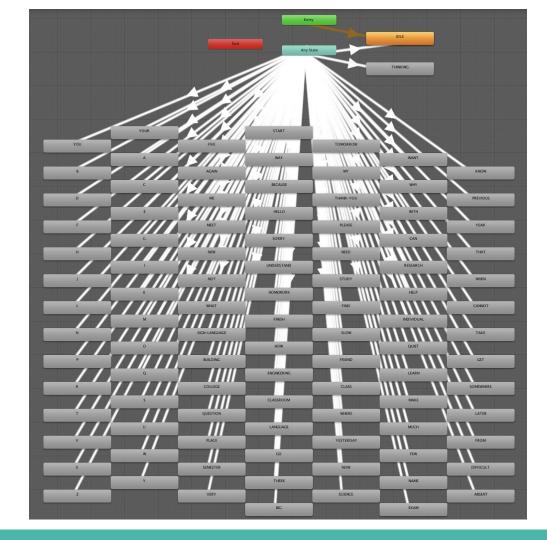


- Functions of the game engine:
  - Display animations
  - Integration of text-to-speech, speech-to-text, and (possible) audio-to-WAV API

	Minimum RAM	Compatible with Linux-based ARM64	Compatible with x86_64	Community Support for Programming		
Unity	None	No	Yes	Full		
Unreal Engine 4	8 GB	Yes	Yes	Limited		
Godot	4 GB	No	Yes	None		

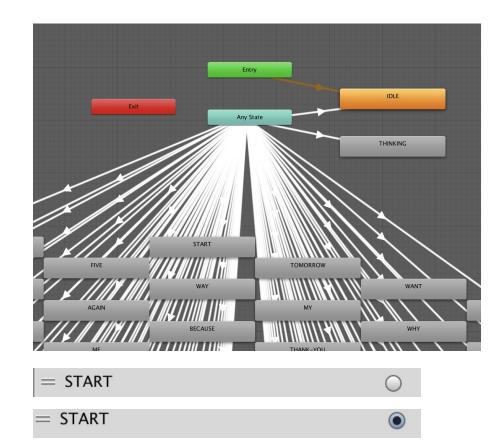
## **Video Rendering**

- Dynamic state machine
- Hash Table used to map word as string to corresponding animation
- Trigger parameter used to start an animation



## **Video Rendering**

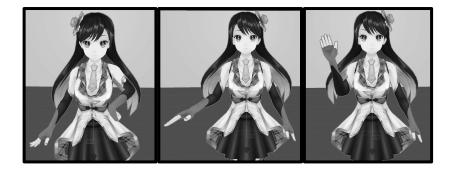
- Dynamic state machine
- Hash Table used to map word as string to corresponding animation
- Trigger parameter used to start an animation



↑ Sample trigger parameter.

### **Video Rendering**

- Dynamic state machine
- Hash Table used to map word as string to corresponding animation
- Trigger parameter used to start an animation



#### "IDLE" $\rightarrow$ <transition> $\rightarrow$ "HELLO"

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### **Extra Internal Processes**

- Vocabulary to Hashtable
  - To map each word to an animation.
- Microphone Module within Unity
  - To capture audio sounds from the microphone.
- Watson API request call for Speech to Text service
  - To generate a Speech to Text translation and store it in a JSON file.
- JSON Parsing
  - To transfer the translation from JSON to text file.
- OpenNMT Translation Call
  - To translate the translation from English to ASL.

## Class Diagram on UDOO

up	odate_canvas : MonoBehavior	
Те	xtMeshProGUI tmp -	
	ol isInCoroutine	
vo	id Start()	
vo	id Update()	
IEr	numerator DisplayHandler()	
	numerator StartDisplay()	

update_anim : MonoBehavior		update_camera : MonoBehavior	
Animator anim Hashtable ht		AudioSource audioSource	
string[] sentence string[] devices Coroutine coroutine		void Start() void Update()	
int hashsize bool startTranslate bool animInProgress		output	
bool micRecording bool isInWaitanim		List <results> results int result_index</results>	
void Start() void Update() void OnGUI()		results	
IEnumerator WaitForAudio() IEnumerator KillGame() IEnumerator AnimHandler()	<u> </u>	List <alternatives> alternatives bool final</alternatives>	
IEnumerator Waitanim(string) void SetHashtable() float GetTimestamp(string)		alternatives	
void Translate() void CallProcess()		float confidence string transcript	

### **Challenges & Issues - Hardware**

- SBC architecture compatibility (**Solved**)
- FPGA difficulty for soldering and programming given timeframe (**Solved**)
- USB Port (Solved)
- I<sup>2</sup>S compatibility for microphone (**Solved**)
- Lack of 3D printed enclosure
- Limited disk drive size

### **Challenges & Issues - Software**

- Granularity-based OpenNMT (trial and error) (**Solved**)
- Bleu Score 3-/4- gram calculation (short sentences)
- Serial Communication between Udoo and Arduino (Solved)
- Utilization of command prompt within Unity (Solved)
- Finding compatible microphone software to interface with Unity (**Solved**)

### **Administrative**

### **Work Distribution**

Member	Embedded	Machine Translation	Graphics Rendering	Integration
Gustavo Camero	Secondary	Secondary	Secondary	Primary
Luis Hurtado	Secondary	Primary		Secondary
Michael Loyd		Secondary	Primary	Secondary
Jared Spinks	Primary			Secondary

### **Proposed Project Budget**

Part	Supplier	Unit Cost	Quantity	Cost
NVIDIA JETSON	NVIDIA	\$95.96	1	\$95.96
Altera Cyclone IV	UDOO	\$8.90	1	\$8.90
MSP430FR6989	Mouser	\$7.86	1	\$7.86
MEMS Microphone SPH0645LM4H	Adafruit	\$6.95	1	\$6.95
IR Receiver TSOP38238	Adafruit	\$1.95	1	\$1.95
WiFi Module	Amazon	\$15.00	1	\$15.00
Display Monitor	Amazon	\$59.99	1	\$59.99
РСВ	JLCPCB	\$50	1	\$50
Miscellaneous				\$200
Total	Supplier			\$446.61

### Actual Project Budget

			-	
Part	Supplier	Unit Cost	Quantity	Cost
UDOO x86 Advanced Plus	UDOO	\$176.00	1	\$176.00
Power Supply	UDOO	\$8.90	1	\$8.90
PCB/MCU	JLCPCB	\$19.07	1	\$19.07
IR Receiver	Adafruit	\$1.95	1	\$1.95
Display	Amazon	\$59.99	1	
Snowball Microphone	Blue Designs	\$49.99	1	
LCD	Amazon	\$5.99	1	
IR Remote	Adafruit	\$4.95	1	
Miscellaneous				\$132.93
Total		\$326.84		\$338.35



