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University of Central Florida Senior Design II Critical Design Review

Group 13

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Overview

Motivations & Technical Objectives		Component Selection & System Design		-	Challenges to Overcome	
Or what are we on what's the point'	0	Or what is the fas functional prototy		Or how have our out thus far and us to do?		
	R&D		APP		WOO	
NIT		CS&D		OUCH		
	Research & Design Plan		System Integr The User Inter		Administrative Details	
	Or what are the p boundaries of the		Or what will the look like and ho together?	e overall system ow is it tied	Budgets, schedules, roles & responsibilities - as per ABET.	

What is the B3?

Automated Beverage Mixer

A personal mixologist for classy and exotic cocktails

Autonomous Delivery Bot

(+)

A dedicated drink-running bot for ready, continuous and convenient service System Integration Software & UI

A seamless user-interfact for easy event-hosting

(+)

Bartender Butler Bot

An integrated luxury home-appliance for tireless party hosts, posh socialites, and robotics enthusiasts alike



Motivations

45%

The Core Problem is Relatable

The best and worst aspects of being a good and dutiful partymaking host resonate with us:



The Technical Challenges are Alluring

The core problem demands a comprehensive multi-faceted technical approach which yields a bounty of open-ended design questions: **15**%

The Commercial Space is Enticing

The prototype & development journey to and beyond commercial validation of a minimally viable product is itself intrinsically exciting:

• Taking care of guests is work

- Missing out on conversations, games, or moments for dutiful partymaking errands
- "I'll fetch us another round!"
- "Oh, what did I miss?"

• Automation of beverage services

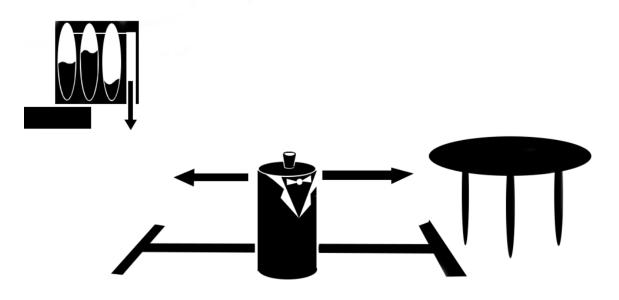
- Autonomous package delivery
- System integration for simple & seamless user experience
- Packaging for functionality vs. manufacturability vs. aesthetics

• Bespoke designs vs. modular approach to scaling

- New & empirically derived marketready design objectives
- New & improved technical challenges



Key Objectives



Overall

 Automate the multistep process of mixing and delivering a beverage across a predefined path

Corollaries

- Maximize the number of off-the-shelf or open-source subsystems
- Minimize the number of mechanical subsystems
- Minimize the overall cost of the system



Research

Bartendro

- Raspberry Pi
- Peristaltic Pumps

SirMixaBot

Peristaltic Pumps

RaspRobot

OpenCV

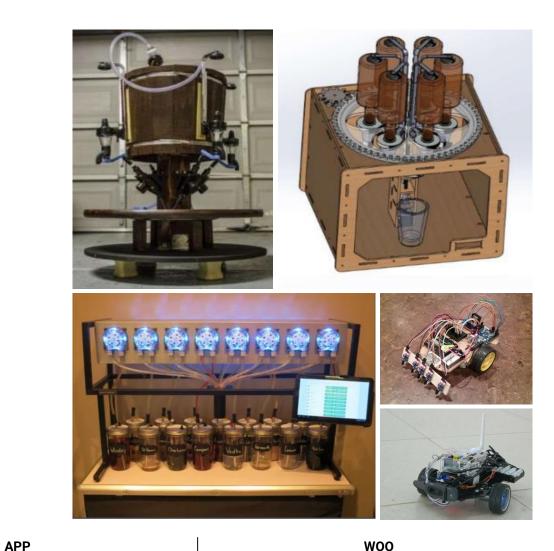
Object Tracking Technique

Arduino Elliot

- IR Sensor Array
- PID Line Following

R&D

CSD



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Requirement Specs

CSD

		Unit	Requirement	Achieved?
1	Max. Avg. Bartender Configuration Time	Minutes	< 10	
2	Ordering Time	Minutes	< 1	
3	Beverage Mixing Time	Minutes	< 2	
4	Delivery Time	Minutes	< 5	
5	Min. Capacity for Beverage Ingredients	Ingredients	> 3	✓
6	Drink Accuracy	% Target Vol.	< 5%	
7	Delivery Range	Meters	> 10	
8	Charge Lifespan	Minutes	> 90	
9	Obstacle Collisions	Num/journey	< 3	
10	Bartop Appliance Dimensions Target	cm ³	< 50,000	
11	Total Appliance Cost	USD	< \$1500	 ✓
R&D	APP		woo	

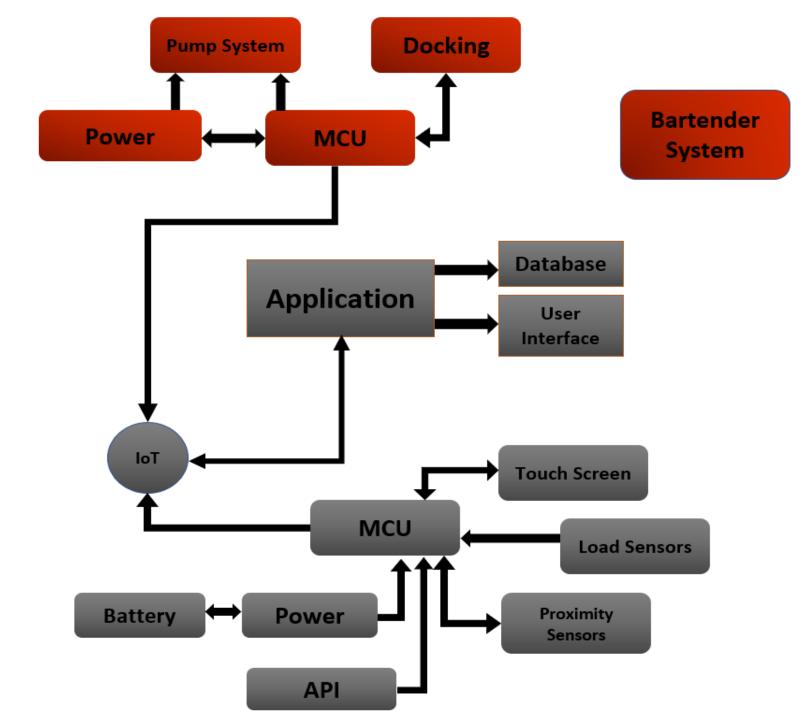
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THE BARTENDER

Sub-System Highlight



BARTENDER: Hardware

Microcontroller

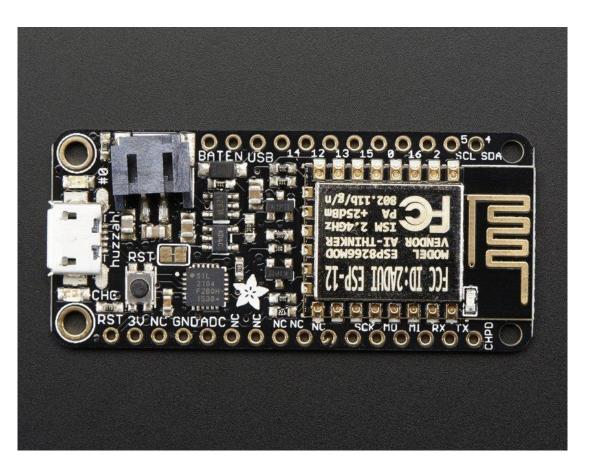
- HUZZAH Feather (Adafruit)
- ESP8266 (Espressif)

Dispensing Recipe

- Peristaltic Pumps (Adafruit)
- Silicon Tubing (McMaster-Carr)
- Opto-Coupled Relays (Songle)
- DC Motor Driver (Texas Inst.)
- 74HC4051 8-Channel (Texas Inst.)

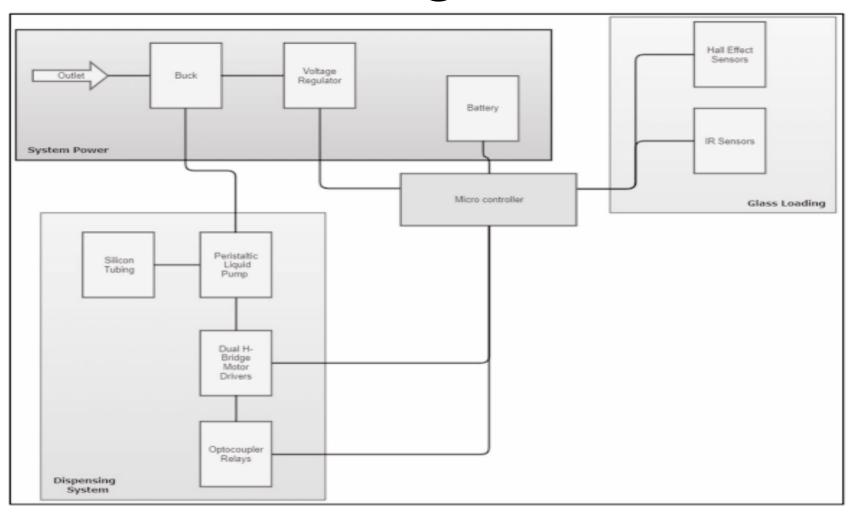
Docking/Alignment Check

HC-SR04 UltraSonic Proximity (ElecF)





BARTENDER: Design



INIT CSD APP WOO

BARTENDER: Firmware

Connect to IoT Hub

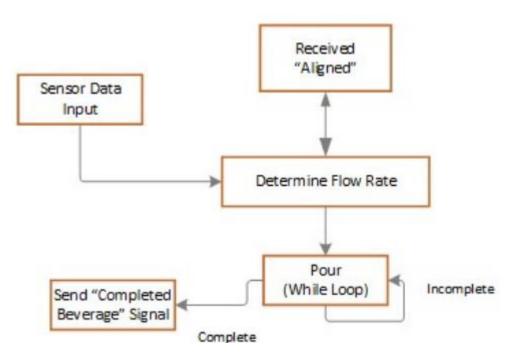
- DHCP IP assignment (WiFi)
- Connect to broker & subscribe to data topics (MQTT)

Readiness Checks (Loop)

 Validate container alignment with nozzle (ADC)

Dispensing Recipe

- Receive beverage order (MQTT)
- Sequential pump action (PWM)
- Release for delivery (MQTT)





BARTENDER: Status

(Breadboard) Prototype/Firmware

- Power, relays, & motor drivers OK
- Connection to WiFi & MQTT OK
- Pump control via PWM OK
- Arbitrary recipe fulfillment via serial NO
- Pump control via MQTT NO
- ...

PCB Design

- Module schematics & footprints OK
- SMD component vendor sourced OK
- Initialized schematic OK
- Initialized layout NO
- ...



BARTENDER: Status

Structural

- CAD for base components OK
- MVP CAD prototype OK
- Components sourced/ordered OK
- Initial structure manufacturing NO
- Initial structure validation NO
- ...

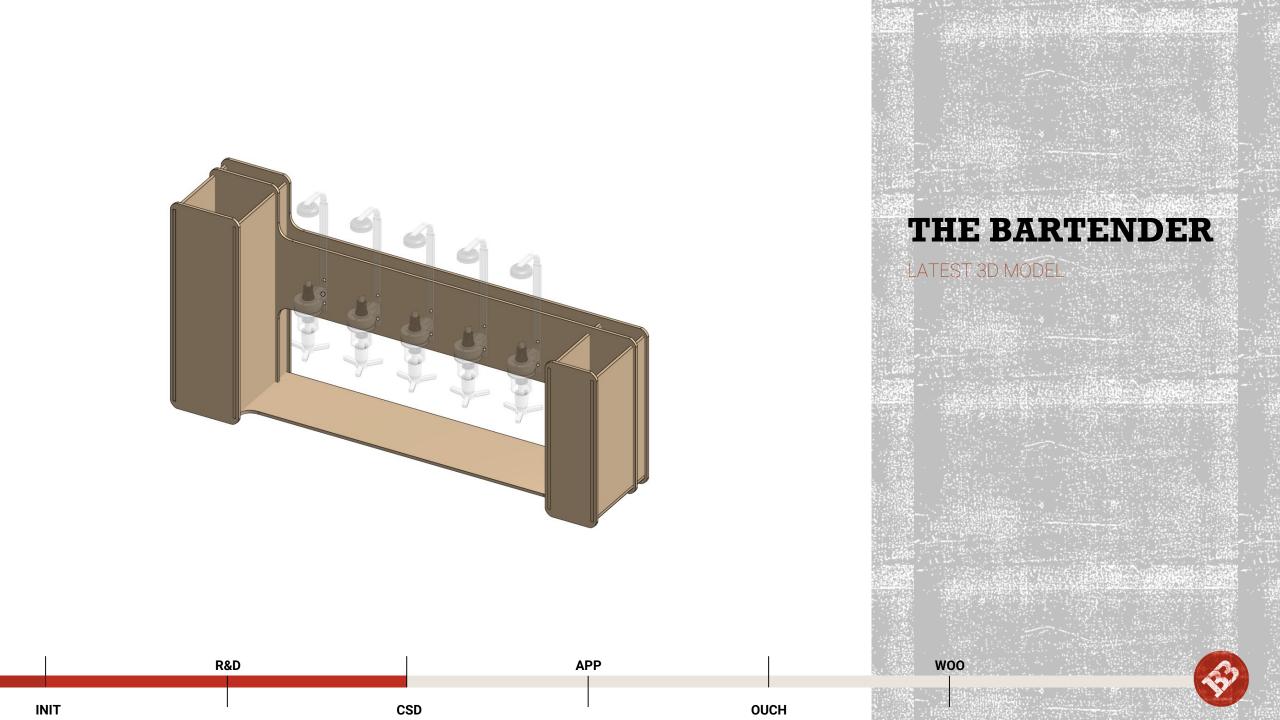
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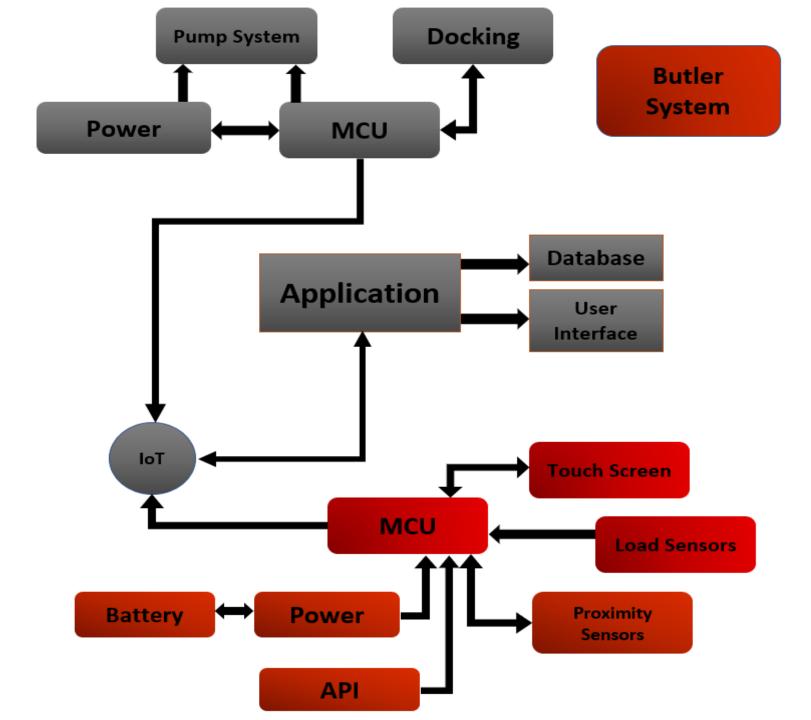
Overall Integration

- MQTT tags pre-defined OK
- MQTT tags validated, live demo OK









THE BUTLER

Block Diagram Highlight



BUTLER: Hardware

Motorized Platform

Create 2.0 (iRobot)

Navigation "Firmware"

- Raspberry Pi 4.0 + Raspbian Lite
- IR photodiode (Generic)
- TAL221 Load Cell (HTC-Sensors)
- HX711 24-Bit ADC (Avia)

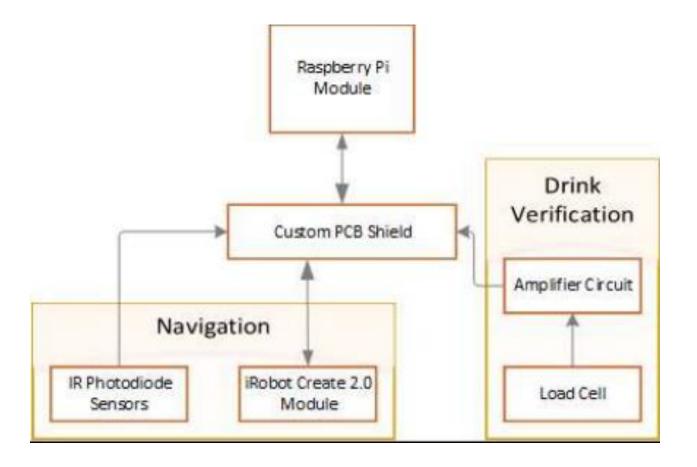
Structure

- ¼" MDF (HomeDepot)
- Aluminum T-slot (8020 Inc.)





BUTLER: Design





BUTLER: Firmware

Navigation

- Line following with PID controller
 - IR Sensors
 - Raspberry Pi + Python
- Built-in docking feature

Cup Detection (Override Interrupt)

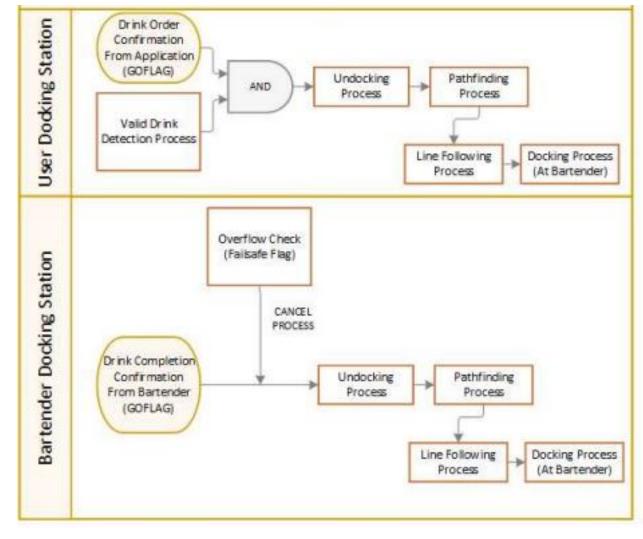
Load cell monitoring

Communication with MQTT

- Start/End Navigation
 - Docking at endpoints

R&D

Cup Presence + Empty/Full



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APP

BUTLER: Status

(Breadboard & Pi) Prototype/Firmware

- Load cell sensor validation OK
- IR sensor validation OK
- iRobot serial interface motion control OK
- iRobot motion control via Python OK
- iRobot preset path & docking OK
- IR sensor array integration via Python NO

• ...

PCB Design

- Module schematics & footprints OK
- SMD component vendor sourced OK
- Initialized schematic NO
- Initialized layout NO

• ...



BUTLER: Status

Structural

- CAD for base components OK
- MVP CAD prototype OK
- Components sourced/ordered OK
- Initial structure manufacturing NO
- Initial structure validation NO
- ...

Overall Integration

R&D

- MQTT tags pre-defined OK
- Transition development to Pi OK
- MQTT tags validated, live demo OK

CSD

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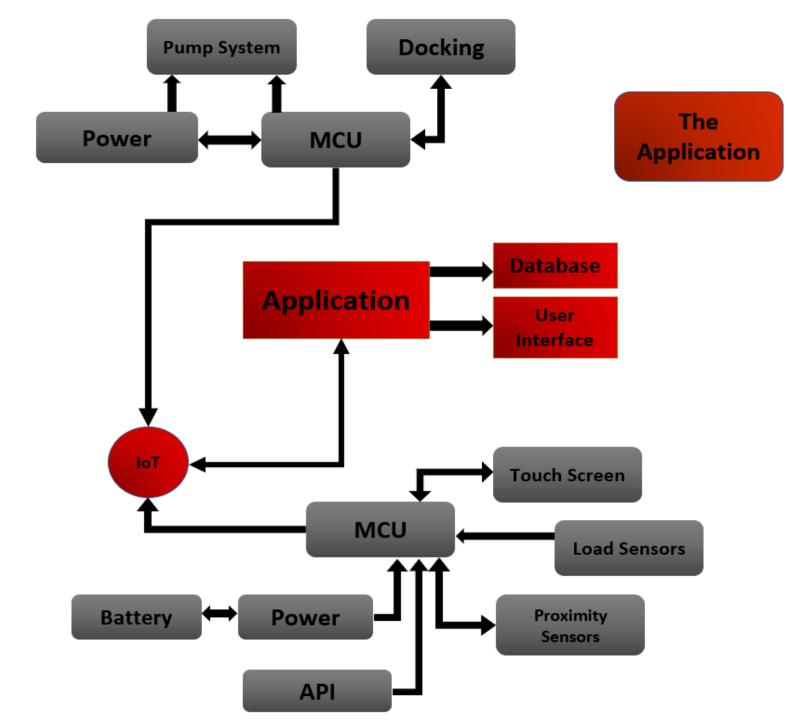


SUB SYSTEM 2 THE BUTLER

LATEST 3D Model

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THE APPLICATION

Block Diagram Highlight

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APPLICATION: Building Blocks

Operating System / Environment

Linux Raspbian Lite (bare bones)

"Internet of Things" Platform

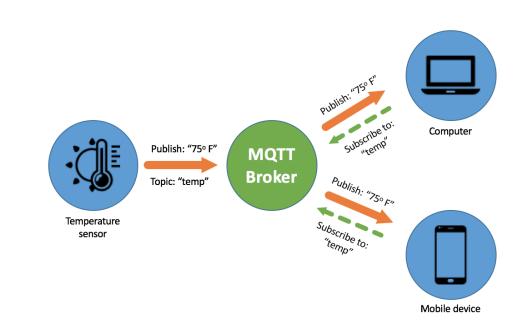
Eclipse Mosquitto (MQTT)

Persistent Database

SQLite3

Programming Language

- Python 3.7.4
 - PyQT5 (GUI) lib
 - Paho (MQTT) lib
 - Sqlite3 lib





APP: Status of Backend Env.

Operating System & Runtime Environment

- Flash OS, strip to OS bare essentials, enable GPIO functions OK
- Install Python, libraries, configure Git repos
 OK

MQTT Broker Configuration

- Install, enable service, configure for maximum QoS OK
- Validate errorless machine-to-machine data transfer between subsystems OK

SQL Database Configuration

- Install, enable service OK
- Format tables, populate tables with basic entries, validate core query structures OK

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int	name
rec	ipes
id	i
id	i pe_name stri
ic re	e cipe_name str
id rec ing	i pe_name stri



APP: Status of GUI

Graphical User Interface

- Formalize visual design & generate UI basis files from development toolkit OK
- Translate/Port to Python & PyQT5 OK
- Link basic button functionalities

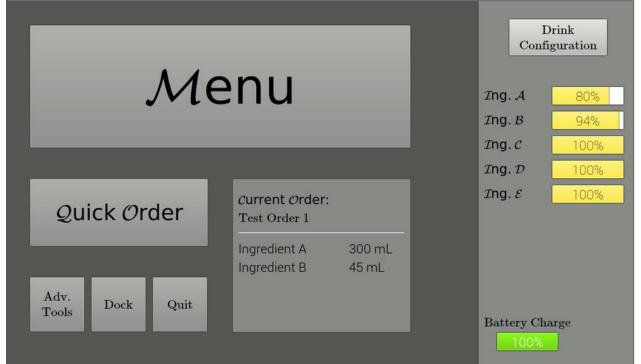
 i.e. "exit all processes" OK
 i.e. confirmation dialogues OK
- Instantiate primary Window & actions OK
- Instantiate menu shell & actions NO

• ...

• ...

Core Logic

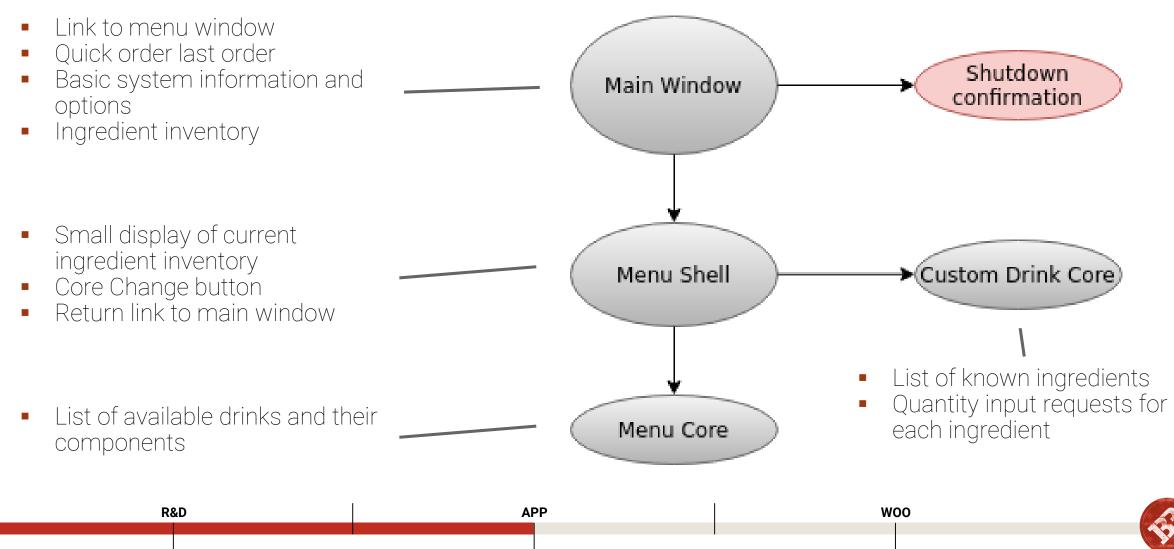
- Send/receive data from MQTT OK
- Send/receive data from SQLite OK
- Live GUI refresh on data updates OK
- Subsystem management logic NO





APPLICATION: GUI Breakdown

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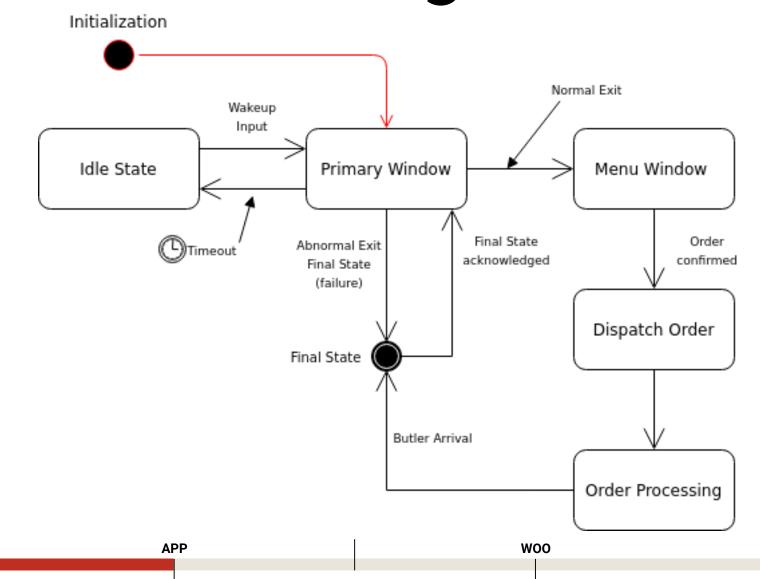
APPLICATION: State Diagram

Idle State: Lack of user input or relevant system processes **Primary Window**: Constantly checks various system states Menu Window: Queries SQL database to offer relevant information to the user Dispatch Order: Received confirmation from user. Initiates Butler movement **Order Processing:** Constantly

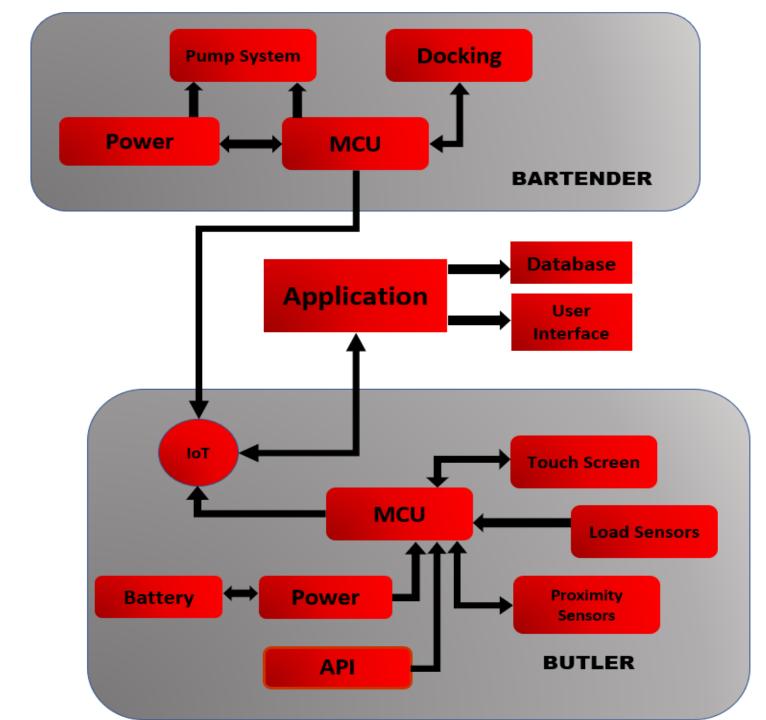
monitors Butler and Bartender processes until end of delivery.

R&D

CSD



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OVERALL SYSTEM SUMMARY

& Notes on Integration

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Challenges to Overcome

Simultaneous Development Timelines (& Overall System Integration)

- Radically distinct, individually complex subsystems
- Maintaining alignment for concurrent/dependent development goals

Team Experience

- Steep learning curves for CAD software &
- Lack of familiarity with sensor libraries, programming languages = addtl hours spent

• ...

Conflicting Considerations Approaches

- Optimum Functionality vs.
- Manufacturability/Deployability vs.
- Aesthetics/Ergonomics



Health and Safety Standards

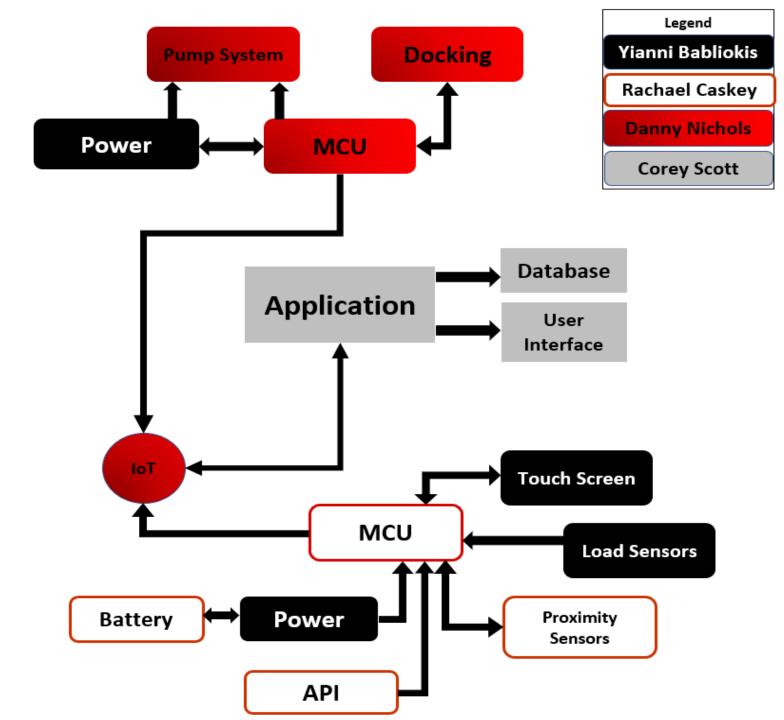
- Food Safety NSF/ANSI 25
 - The purpose of this standard is to establish the minimum food protection and sanitation guidelines
- Drinking Water NSF/ANSI 61
 - the standard that covers drinking water system components
- Fire Safety and Emergency NFPA
 - the fire safety standard that provides symbols used to effectively communicate fire safety, emergency, and associated hazards information.

Digital Standards

- Wireless Communication IEEE 802.11
- MQTT v5.0 standards ISO/IEC PRF 20922







SYSTEM DIAGRAM

Responsibilities Highlight

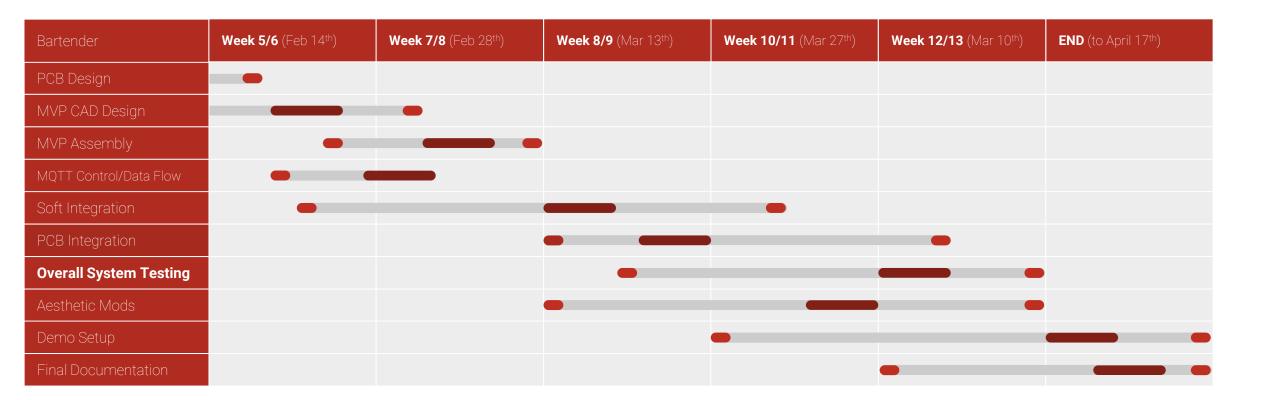


ADMINISTRATION: Roles & Responsibilities

Assisted: Main: 🗸 Internet of Butler Butler Butler Bartender Butler Butler Butler Bartender User Butler Pump Task Things Database Application Proximity Battery Power Power Load Touch MCU MCU API System Interface Platform System Sensors System System Sensors Screen Ľ. Yianni \checkmark **Babiolakis** Rachael \checkmark \checkmark Caskey Ľ Danny Ľ. V Nichols ĴÊ, ₿ġ. Corey ₿ġ, \checkmark Scott

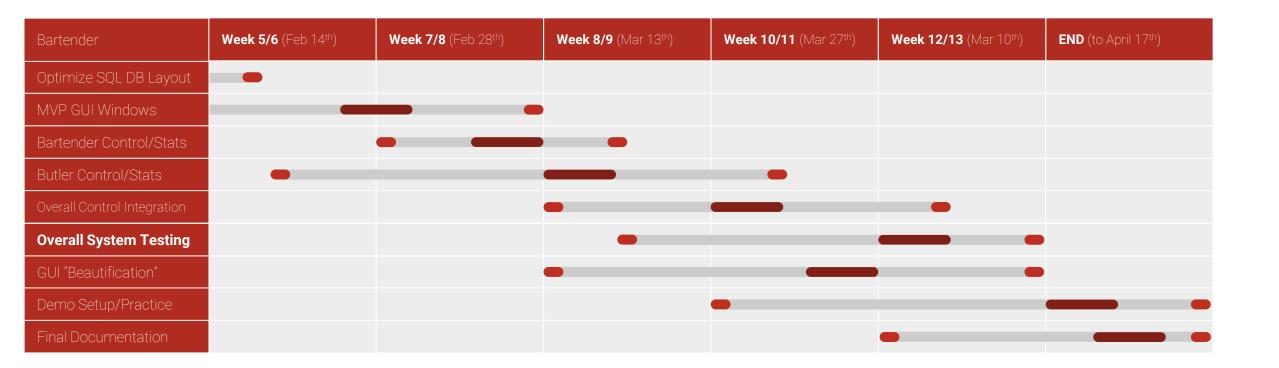


Bartender/Butler Schedule



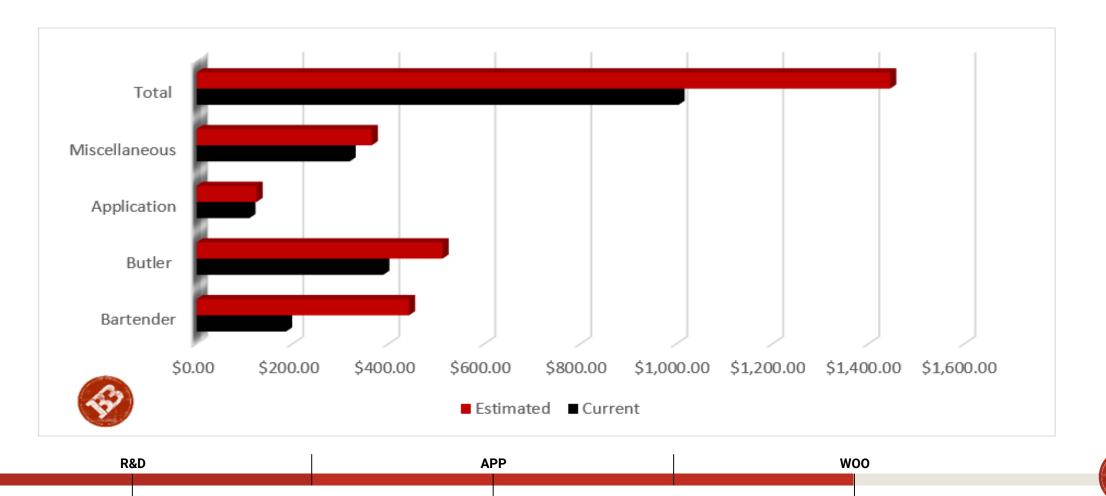


Application (Integration) Schedule





Budget



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ADMINISTRATION: Progress Percentage

